# Instruction Manual Model CXT-IR



# **CXT-IR Gas Sensor**

This manual covers all CXT-IR Sensors

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# **Table of Contents**

1. Intro	oduction	1
1.1	Description	1
1.2	Modular Design	2
1.2.		
1.2.	2 Field Replacement Sensor	4
1.3	CXT Wireless Network	
1.4	Battery Pack Options	
	1 Teledyne Detcon's Smart Battery Pack	
	2 D Cell Lithium Battery Pack	
	allation	
2.1	Hazardous Locations Installation Guidelines for Safe Use	
2.2	Sensor Placement	
2.3	Sensor Contaminants and Interference	
2.3	Sensor Containmants and Interference	
2.5	Electrical Installation	
2.5		
2.5.	Initial Start Up	
2.6	1	
2.6.		
	2 Initial Operational Tests	
3. Opc	Programming Magnet Operating Instructions	
3.1	Operator Interface	
3.3	Normal Operation	
3.4	Calibration Mode	
3.4		
3.4.		
3.5	Program Mode	
3.5	•	
3.5.	6 6	
3.5.		
3.5.		
3.5.	1	
3.5.	1	
3.5.		
3.5.		
3.5.	-	
3.6	Fault Diagnostic/Failsafe Feature	
	dbus <sup>TM</sup> Communications	
4.1	General Modbus <sup>TM</sup> Description	
4.1.		
4.1.		
4.2	Modbus <sup>TM</sup> Register Map and Description	
4.2	- · ·	
4.2.	8	
	vice and Maintenance	
5.1	Calibration Frequency	
5.1 5.2	Visual Inspection	
5.2 5.3	Condensation Prevention Packet	
5.5 5.4	Replacement of batteries/battery pack	
5.4.		
5.4. 5.5	6	
	Replacement of Plug-in Sensor	
5.6	Replacement of ITM – Aluminum Junction Box	



6.	Troubleshooting Guide	
	Customer Support and Service Policy	
	CXT-IR Sensor Warranty	
	Appendix	
	9.1 Specifications	
	9.2 Spare Parts, Sensor Accessories, Calibration Equipment	
	Revision Log	

# **Table of Figures**

Figure 1 Sensor Cell Construction	1
Figure 2 Principle of Operation	2
Figure 3 Sensor Assembly Breakaway	
Figure 4 ITM Circuit Functional Block Diagram	
Figure 5 Sensor Assembly Front View	4
Figure 6 Plug-in Sensor	
Figure 7 Smart Battery Pack	6
Figure 8 Quad Battery Charger	6
Figure 9 D-Cell Lithium Battery Pack	7
Figure 10 CXT-IR Sensor with D or Smart Battery Pack Mounting Dimensions	
Figure 11 Terminal Interconnect for Smart Battery Pack	13
Figure 12 Magnetic Programming Tool	15
Figure 13 Magnetic Programming Switches	15
Figure 14 Menu Flow Chart	17
Figure 16 Modbus <sup>™</sup> Frame Format	24
Figure 17 Battery Orientation Diagram	
Figure 18 Sensor Cell and ITM Mating	

# **List of Tables**

Table 1 Exception Codes	24
Table 2 CXT-IR Register Map	25
Table 3 Spare Parts, Sensor Accessories, and Calibration Equipment	
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# 1. Introduction

# 1.1 Description

Teledyne Detcon Model CXT-IR combustible gas sensors are non-intrusive "Smart" sensors designed to detect and monitor combustible hydrocarbon gases in the air with a detection range of 0-100% LEL (Lower Explosive Limit). The sensor features an LED display of current reading, fault and calibration status. A primary feature of the sensor is its method of automatic calibration, which guides the user through each step via fully scripted instructions illustrated on the LED display.

The microprocessor-supervised electronics are enclosed in an encapsulated module and housed in an explosion proof casting.

The unit includes:

- a built in 2.4GHz radio to transmit status wirelessly to a controller,
- a four character alpha/numeric LED to display sensor readings, and
- a menu-driven interface when the hand-held programming magnet is in use.
- an optional strobe

#### Non-Dispersive Infrared (NDIR) Optical Sensor Technology

The sensor technology is designed as a miniature plug-in replaceable component, which can easily be changed out in the field.

The NDIR sensor consists of (Figure 1):

- one infrared lamp source,
- two pyroelectric detectors (active and reference),
- and one optical gas sample chamber.

The lamp source produces infrared radiation, which interacts with the target gas as it is reflected through the optical gas sample chamber. The infrared radiation contacts each of the two pyroelectric detectors at the completion of the optical path. The active pyroelectric detector is covered by a filter specific to the part of the IR spectrum where the target gas absorbs light. The reference pyroelectric detector is covered by a filter specific to the non-absorbing part of the IR spectrum. When the target gas is present, it absorbs IR radiation and the signal output from the active detective decreases accordingly. The reference detector output remains unchanged. The ratio of the active and reference detector outputs are then used to compute the target gas concentration.

The technique is referred to as non-selective and may be used to monitor most any combustible hydrocarbon gas. Unlike catalytic bead type sensors, Teledyne Detcon IR sensors are completely resistant to poisoning from corrosive gases and can operate in the absence of an oxygen background. The sensors are characteristically stable and capable of providing reliable performance for periods exceeding 5 years in most industrial environments.



Figure 1 Sensor Cell Construction



#### **Principle of Operation**

The target gas diffuses through a sintered stainless steel flame arrestor and into the volume of the sample gas optical chamber. An alternating miniature lamp provides a cyclical IR radiation source, which reflects through the optical gas sample chamber and terminates at the two pyroelectric detectors. The active and reference pyroelectric detectors each give an output which measures the intensity of the radiation contacting their surface. The active detector is covered by an optical filter specific to the part of the IR spectrum where the target gas absorbs light. The reference detector is covered by a filter specific to the non-absorbing part of the IR spectrum. When present, the target gas absorbs a fraction of the IR radiation and the signal output from the active detector decreases accordingly. The signal output of the reference detector remains unchanged in the presence of the target gas. The ratio of the active/reference signal outputs is then used to compute the target gas concentration. By using the ratio of the active/reference signal outputs, measurement drift caused by the changes in the intensity of the IR lamp source or changes in the optical path's reflectivity is prevented (Figure 2).



Figure 2 Principle of Operation

#### **Performance Characteristics**

The IR sensor maintains strong sensitivity to most all combustible hydrocarbon gases within the LEL range. When compared with the typical catalytic bead LEL sensor, the IR sensor exhibits improved long-term zero and span stability. Typical zero calibration intervals are quarterly to semi-annual and typical span intervals are semi-annual to annual.

NOTE: Actual field experience is always the best determination of appropriate calibration intervals.
<b>NOTE:</b> The CXT-IR sensor will not respond to combustible gases that are not hydrocarbons, such as H <sub>2</sub> ,
NH <sub>3</sub> , CO, H <sub>2</sub> Setc. It can only be used to measure hydrocarbon type gases.

The IR sensor generates different signal sensitivity levels for different combustible hydrocarbon target gases. Unless otherwise specified the CXT-IR sensor will be factory calibrated for methane service.

#### **1.2 Modular Design**

The Model CXT-IR Sensor Assembly is completely modular and is made up of four parts (Figure 3)

- 1) CXT-IR Intelligent Transmitter Module (ITM)
- 2) Plug-in infrared Sensor
- 3) CXT Series Bottom Housing
- 4) Splash Guard



Figure 3 Sensor Assembly Breakaway



**NOTE:** All metal components are constructed from electro polished 316 Stainless Steel in order to maximize corrosion resistance in harsh environments.

### 1.2.1 CXT-IR Intelligent Module

The Intelligent Transmitter Module (ITM) is a fully encapsulated microprocessor-based package that accepts a plug-in field replaceable combustible gas sensor.

Circuit functions include (Figure 4):

- extensive I/O circuit protection,
- sensor pre-amplifier,
- on-board power supplies,
- microprocessor,
- LED display,
- magnetic programming switches,
- built-in 2.4GHz radio

Magnetic program switches located on either side of the LED Display are activated by a hand-held magnetic programming tool, allowing a non-intrusive operator interface with the ITM. The program switches allows calibration without declassifying the area.



Figure 4 ITM Circuit Functional Block Diagram



Figure 5 Sensor Assembly Front View

#### 1.2.2 Field Replacement Sensor

Teledyne Detcon's infrared gas sensors are field proven, plug-in sensors with over-sized gold-plated connections that eliminate corrosion problems. The sensor can be accessed and replaced in the field easily by releasing the locking screw and unthreading the splashguard adapter assembly.

**NOTE:** Teledyne Detcon's combustible sensors have a long shelf life and are supported by an industry-leading warranty.



Figure 6 Plug-in Sensor



# 1.3 CXT Wireless Network

The CXT-IR sensor utilizes a transceiver radio, based on the IEEE 802.15.4 standard. The transceiver operates at 2.4 GHz using DSSS encoding for robustness. DSSS was initially used by the military to resist jamming but later was widely adopted for wireless implementations since it was robust in noisy environments. DSSS transmits data across a wider frequency range than the actual frequency range required for the information. This operation minimizes cross talk and interference from other transceivers and is less susceptible to noise from other sources.

The IEEE 802.15.4 defines 16 separate RF Channels that can be used in the 2.4 GHz range. The default channel is 1 but can be changed if there is RF interference or if there is an existing network using that channel. Transceivers will only respond to other transceivers with the same RF Channel.

**NOTE:** If there are multiple CXT-IR networks in the same vicinity, each system must reside on a different RF Channel to keep data from one appearing on the other system.

The 802.15.4 standard also implements a mesh network allowing any CXT-IR transceiver to relay or repeat data between adjacent neighbors. This makes the network very robust and provides the following immediate benefits.

- Allows re-routing of data in case of loss of a transceiver
- Allows re-routing around wireless obstacles
- Longer distances between transceivers because data can "hop" from one transceiver to the next
- Included in sensor, controller and alarm station transceivers
- CXT-IR transceivers can be deployed with less concern about physical location.

### **1.4 Battery Pack Options**

The CXT-IR can be powered by a battery pack that enables the IR to be remotely mounted without the need for external cabling. Teledyne Detcon offers several battery pack options that are factory installed. Contact Teledyne Detcon for more information on these options.

#### 1.4.1 Teledyne Detcon's Smart Battery Pack

The Teledyne Detcon's plug-in Smart Battery Packs provides an output of 12VDC (See Figure 7). There are two versions of the Smart Battery Pack. The first one is the 12V 2200mAh battery Pack (Teledyne Detcon's part number 976-0BP303-120) and the second is the 12V 2900mAh Battery Pack. The CXT-IR monitors the battery pack for remaining battery life. The battery packs consist of rechargeable Lithium-Ion batteries and are equipped with integrated safety electronics that include a fuel gauge, voltage monitor, and current and temperature monitoring circuits. This "smart" circuitry continuously monitors the battery's condition and reports critical status information to the wireless transceiver via the Modbus™ registers. The battery packs are designed to plug into an 8-pin Beau connector on the Terminal Board that the sensor is connected to. The battery Pack and Terminal Board are housed in Teledyne Detcon's Aluminum Condulet to protect them from exposure to outside elements and still provide Class I Div 1, C, and D approvals. Operating periods before recharge will vary based on sensor attached but can be as long as 3.5 months for the 12V 2200mAh battery pack, and 5 months for the 12V 2900mAh battery pack may be hazardous to personnel or the environment and will void the warranty.



Figure 7 Smart Battery Pack

#### **Quad Battery Charger (Optional)**

Teledyne Detcon's Smart Battery Pack can be charged as needed using Teledyne Detcon's optional Quad Battery Charger which can charge up to four battery packs at one time. The Quad Battery Charger comes with a plugin AC/DC adapter that plugs into a standard 100-240VAC outlet for power. The DC end of the adapter plugs into the DC power jack of the charger providing 24VDC. The Quad Battery Charger has four charging ports, each with 8-pin Beau connectors for battery pack connection. The ports and connectors are keyed to prevent incorrect positioning and connection. Each port has its own "FAULT" LED indicator and "CHARGE" LED indicator and will display either a red light or green light depending on the status of each battery being charged. Charging times will vary depending on the charge state of each battery pack, but a full charge of a depleted battery pack can take up to 24 hours.



Figure 8 Quad Battery Charger



### 1.4.2 D Cell Lithium Battery Pack

The D Cell Lithium Battery Pack (Figure 9) contains five 3.6V Lithium Primary D size batteries which are not re-chargeable. This battery pack provides the unit with 18 volts. The batteries are contained in a battery holder mounted in Teledyne Detcon's aluminum explosion proof condulet. The CXT-IR sensors will operate up to 9 months before battery replacement is needed. The battery Pack and Terminal Board are housed in Teledyne Detcon's Aluminum Condulet to protect them from exposure to outside elements and still provide Class I Div 1, C, and D approvals.



Figure 9 D-Cell Lithium Battery Pack



# 2. Installation

# 2.1 Hazardous Locations Installation Guidelines for Safe Use

**NOTE:** The CXT-IR assembly with strobe is not rated for Class I Division 1 or Class I Zone 1 applications. The following guidelines only apply to a CXT-IR assembly *without* a strobe.

- **1.** Install the sensor only in areas with classifications matching the approval label. Follow all warnings listed on the label.
- 2. Do not remove the junction box cover while in the classified are unless it is conformed the there is no explosive gas levels in the area.
- 3. A good ground connection should be verified between the sensor's metal enclosure and the junction box. If a good ground connection is not made, the sensor can be grounded to the junction box using the sensor's external ground lug. Verify a good ground connection between the junction box and earth ground.
- 4. Proper precautions should be taken during installing and maintenance to avoid the build-up of static charge on the plastic components of the sensor (Splash Guard and Antenna Dome Cover) Wipe with damp cloth on plastic components to avoid static discharge.
- 5. Do not substitute components. Substitution of components may impair the intrinsic safety rating.
- 6. Do not operate the sensor outside of the stated operating temperature limits.
- 7. Do not operate the sensor outside the stated operating limits for voltage supply.
- 8. These sensors meet ATEX standards EN IEC 60079-0:2018, EN 60079-1:2014, EN 60079-11: 2012.
- 9. These sensors have a maximum safe location voltage of Um=30V.
- 10. These sensors pass dielectric strength of 500VRMS between circuit and enclosure for a minimum of 1 minute at a maximum test current of 5mA.
- 11. The CXT-IR must only use IR cell model 371-IR1II1-000 or 371-IR1II1-EXD. No other cell shall be used.
- 12. For North American use only, the CXT-IR may use Teledyne Detcon P/N 360-TL5930-000 batteries (Tadiran Model TL-5930). The battery holder utilizes 5 of these D cell batteries in series to operate the sensor.
- 13. For North American use only, the CXT-IR may use Teledyne Detcon P/N 360-3S6P00-000 (2200mAh) or P/N 360-3SP00-290 (2900mAh) rechargeable Lithium batteries.
- 14. The CXT-IR contains FCC ID U9O-RF220SU and IC 7084A-RF220SU.
- 15. The CXT-IR complies with FCC Maximum Permissible Exposure (MPE) requirements when used with an approved antenna and the antenna is at least 20cm away from the user. Use of the product closer than 20cm may exceed the MPE limits. Use of any antenna other than the approved antennas will invalidate the certification of the product.
- **16.** The CXT-IR complies with Part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.
- WARNING: CSA certification does not include wireless communication or Modbus used for combustible gas performance. The wireless communication or Modbus may only be used for data collection or record keeping with regard to combustible gas detection. Gas indication and alarm functions for performance are only permitted locally by the detector.



### 2.2 Sensor Placement

Selection of sensor location is critical to the overall safe performance of the product. Six factors play an important role in selection of sensor locations:

- Density of the gas to be detected
- Most probable leak sources within the industrial process
- Ventilation or prevailing wind conditions
- Personnel exposure
- Placement of transmitting antenna
- Maintenance access

#### Density

Placement of sensors relative to the density of the target gas should be located within 4 feet of grade as heavy gases tend to settle in low lying areas. For gases lighter than air, sensor placement should be 4 to 8 feet above grade in open areas or in pitched areas of enclosed spaces.

#### Leak Sources

The most probable leak sources within an industrial process include flanges, valves, and tubing connections of the sealed type where seals may either fail or wear. Other leak sources are best determined by facility engineers with experience in similar processes.

#### Ventilation

Normal ventilation or prevailing wind conditions can dictate efficient location of gas sensors in a manner where the migration of gas clouds is quickly detected.

#### Personnel Exposure

The undetected migration of gas clouds should not be allowed to approach concentrated personnel areas such as control rooms, maintenance or warehouse buildings. A more general and applicable sensor location is combining leak source and perimeter protection in the best possible configuration.

#### Maintenance Access

Consideration should be given to providing easy access for maintenance personnel and the consequences of close proximity to contaminants that may foul the sensor prematurely.

**NOTE:** In all installations the gas sensor should point straight down (refer to Figure 11). Improper sensor orientation may result in false readings and permanent sensor damage.

#### Placement of RF Antenna

Placement of the sensor should have consideration made for line of sight RF transmissions. The devices should be placed in a reasonable proximity to other devices in the network. Obstacles between CXT transceivers can impact RF line-of-sight and may result in communication problems. The CXT sensor should be in view of at least one other transceiver.

#### Additional Placement Considerations

The sensor should not be positioned where it may be sprayed or coated with surface contaminating substances. Painting sensor assemblies is prohibited.

Although the sensor is designed to be RFI resistant, it should not be mounted in close proximity to high-powered radio transmitters or similar RFI generating equipment.

When possible mount in an area void of high wind, accumulating dust, rain, or splashing from hose spray, direct steam releases, and continuous vibration. If the sensor cannot be mounted away from these conditions then make sure the Teledyne Detcon Harsh Location Dust Guard accessory is used.

Do not mount in locations where temperatures will exceed the operating temperature limits of the sensor. Where direct sunlight leads to exceeding the high temperature-operating limit, use a sunshade to help reduce temperature.



# 2.3 Sensor Contaminants and Interference

Teledyne Detcon CXT-IR combustible hydrocarbon gas sensors may be adversely affected by exposure to certain airborne substances. Loss of sensitivity or corrosion may be gradual if such materials are present in sufficient concentrations.

The performance of the IR sensor may be impaired during operation in the presence of substances that can cause corrosion on gold plating. Other inhibiting substances are those that can coat the internal walls of the optical chamber and reduce reflectivity. These include but are not limited to heavy oil deposits, dust/powder, water condensation, and salt formation. Continuous and high concentrations of corrosive gases (such as Cl<sub>2</sub>, H<sub>2</sub>S, HCl ...etc.) may also have a detrimental long-term effect on the sensor's service life.

The presence of such substances in an area does not preclude the use of this sensor technology, although it is likely that the sensor lifetime will be shorter as a result. Use of this sensor in these environments may require more frequent calibration checks to ensure safe system performance.

For the CXT-IR combustible gas sensors there are no known cross-interference gases that are not combustible hydrocarbon gases.

### 2.4 Sensor Mounting

The CXT-IR should be vertically oriented so that the sensor points straight downward (Figure 11). The explosion-proof enclosure or junction box is typically mounted on a wall or pole. Teledyne Detcon provides a selection of standard junction boxes in both Aluminum and Stainless Steel.

**NOTE:** If wall mounting without a mounting plate, make sure to use at least 0.5" spacers underneath the Teledyne Detcon Aluminum Junction-Box's 1/4" mounting holes to move the sensor assembly away from the wall and allow access clearance to the sensor assembly.

**NOTE:** Do not use Teflon Tape or any other type of Pipe Thread material on the <sup>3</sup>/<sub>4</sub>" threads unless the sensor is mounted in a severe or harsh environment. Metal-on-metal contact must be maintained to provide a solid electrical ground path. If Teflon Tape is used the Sensor *must* be externally grounded using a ground strap.

When mounting on a pole, secure the Junction Box to a suitable mounting plate and attach the mounting plate to the pole using U-Bolts. (Pole-Mounting brackets for Teledyne Detcon Junction Boxes are available separately.)







# 2.5 Electrical Installation

The CXT is designed to be battery operated, and normally will not have external cabling or wiring. If the sensor requires external wiring, the sensor assembly should be installed in accordance with local electrical codes. Proper electrical installation of the gas sensor is critical for conformance to electrical codes and to avoid damage due to water leakage.

If a conduit run exists, a drain should be incorporated. The drain allows H<sub>2</sub>O condensation inside the conduit run to safely drain away from the sensor assembly. The electrical seal fitting is required to meet the National Electrical Code per NEC Article 500-3d (or Canadian Electrical Code Handbook Part 1 Section 18-154). Requirements for locations of electrical seals are covered under NEC Article 501-5. Electrical seals also act as a secondary seal to prevent water from entering the wiring terminal enclosure. However, they are not designed to provide an absolute watertight seal, especially when used in the vertical orientation.

**NOTE:** The Teledyne Detcon Warranty does not cover water damage resulting from water leaking into the enclosure.

**NOTE:** Any unused ports should be blocked with suitable <sup>3</sup>/<sub>4</sub>" male NPT plugs. Teledyne Detcon supplies one <sup>3</sup>/<sub>4</sub>" NPT male plug with each J-box enclosure. If connections are other than <sup>3</sup>/<sub>4</sub>" NPT, use an appropriate male plug of like construction material.



*CAUTION*: Do not apply System power to the sensor until all wiring is properly terminated (2.6 Initial Start Up).

#### 2.5.1 Applying Power to the Unit

*CAUTION:* A 24V solar panel is the most common option for supplying external power. A solar panel will recharge the Teledyne Detcon Smart Battery Pack. **DO NOT CHARGE IN A HAZARDOUS LOCATION**. It CANNOT be used with the D-cells. A 24V input with the D-cells will damage the cells.

- 1. Remove the junction box cover
- 2. If external power is to be applied to the unit, connect the incoming 24V to the Connector labeled 'DC INPUT'. Connect 24V to the terminal labeled '24VDC' and Return to the terminal labeled "GND". The Battery Bracket will need to be removed in order to access the connector.
- 3. Install the batteries:

**NOTE:** The Teledyne Detcon Warranty does not cover water damage resulting from water leaking into the enclosure.

a) For units utilizing the 12V Smart Battery Pack or the D-Size Battery Holder/pack, remove the battery cover by unscrewing the top screws and moving the battery cover out of the way. Plug the battery pack into the Terminal Board. Power will be applied, and the unit will proceed to power up (Section 2.6). The battery Packs will only plug in in one orientation. Replace the Battery Cover and tighten the two screws down to secure the battery pack in place.



Figure 11 Terminal Interconnect for Smart Battery Pack

4. Replace the junction box cover after Initial Start Up. Ensure that the cover is screwed down completely and that the Allen Head screw is tightened down to secure the cover in place.

**NOTE:** A 6-32 or 8-32 threaded exterior ground point is provided on most junction boxes for an external ground. If the Sensor Assembly is not mechanically grounded, an external ground strap *must* be used to ensure that the sensor is electrically grounded.

# 2.6 Initial Start Up

#### 2.6.1 Combustible Gas Sensors

Upon completion of all mechanical mounting and installation of the batteries power is now applied to the unit. If the unit is equipped with the optional power switch, power is applied by pushing the switch. Observe the following normal conditions:

- 1. Upon power up, the sensor will momentarily display **SY**, scroll **TELEDYNE DETCON CXT-IR** and will then display the current reading for approximately 5 seconds. A temporary upscale reading may occur as the sensor stabilizes. This upscale reading will decrease to 0% LEL within 1 to 2 minutes of power-up, assuming there is no gas in the area of the sensor.
- 2. After the initial power up, the sensor display will turn off. Thereafter the display will come on once every 10 seconds and will display the current reading for about 2 seconds, and will return to a blank display to conserve battery power.

**NOTE:** In normal operation the display will come on once every 10 seconds, will display the current reading for about 2 seconds, and will return to a blank display to conserve battery power.



#### 2.6.2 Initial Operational Tests

After a warm up period of 1 hour (or when zero has stabilized), the sensor should be checked to verify sensitivity to the target gas.

#### **Material Requirements**

- Teledyne Detcon PN 613-120000-700 700 Series Splash Guard with integral Cal Port and Calibration Wind Guard (P/N 943-000000-000) -OR-
- Teledyne Detcon PN 943-000006-132 Threaded Calibration Adapter OR -
- Teledyne Detcon P/N 943-01747-T05 Teflon Calibration Adapter for highly reactive gases
- Teledyne Detcon Span Gas; 50% of range target gas in balance  $N_2$  or Air at fixed flow rate between 200-500cc/min

#### **NOTE:** Wind Guard must be used when calibrating with the integral cal port to ensure proper calibration.

- 1. Attach the calibration adapter to the Splashguard Adapter Assembly or connect tubing to integral cal port. It is recommended that the Wind Guard (Teledyne Detcon PN 943-000000-000) is installed over the Splash Guard during calibration. Apply the test gas at a controlled flow rate of 200 500cc/min (500cc/min is the recommended flow). Observe that the ITM display increases to a level near that of the applied calibration gas value.
- 2. Remove test gas and observe that the display decreases to 0.
- 3. If a calibration adapter was used during these tests, remove it from the unit, and re-install the Splash Guard. If the wind guard was used, remove the wind guard.

Initial operational tests are complete.

CXT-IR Combustible gas sensors are factory calibrated prior to shipment, and should not require significant adjustment on start up. However, it is recommended that a complete calibration test and adjustment be performed 16 to 24 hours after power-up. Refer to calibration instructions in Section 3.3.



# 3. Operation

# 3.1 Programming Magnet Operating Instructions

The Operator Interface of the Model CXT Series gas sensors is accomplished via two internal magnetic switches located to either side of the LED display (Figure 16). The two switches, labeled **PGM1** and **PGM2**, allow for complete calibration and configuration, eliminating the need for area de-classification or the use of hot permits.



Figure 12 Magnetic Programming Tool

The magnetic programming tool (Figure 15) is used to operate the magnetic switches. Switch action is defined as momentary contact (a swipe), a 3 second hold, and a 10 second hold. (Hold times are defined as the time from the point when the arrow prompt appears. Swiping the magnet does not display the prompt.) For momentary contact use, the programming magnet is briefly held over a switch location, or swiped. For 3 second hold, the programming magnet is held in place over the switch location for three seconds. For 10 second hold, the programming magnet is held in place over the switch location for 10 seconds. The 3 and 10 second holds are generally used to enter calibration/program menus and save new data. The momentary contact is generally used to move between menu items and to modify set-point values. Arrows ( $\triangleleft$  and  $\triangleright$ ) are used on the LED display to indicate when the magnetic switches are activated. The location of **PGM1** and **PGM2** are shown in Figure 16.



Figure 13 Magnetic Programming Switches

**NOTE:** While in the program mode, if there is no magnetic switch interaction after 4 consecutive menu scrolls, the sensor will automatically revert to normal operating condition. While changing values inside menu items, if there is no magnet activity after 3 to 4 seconds the sensor will revert to the menu scroll. If the sensor is in Bump Test mode, the display will remain active.



# **3.2 Operator Interface**

The operating interface is menu-driven by the two magnetic program switches located under the target marks of the sensor housing. The two switches are referred to as **PGM1** and **PGM2**. The menu list consists of three menu items that include sub-menus; normal operation, calibration mode and, program mode.

#### **Normal Operation**

Concentration Reading is displayed once every 10 seconds.

#### **Calibration Mode**

AutoZero

AutoSpan

#### **Program Mode**

View Sensor Status

Mp App ##.## CP App ##.## Rf App ##.##.## RfSw ##.## Modbus<sup>TM</sup> ID ## Serial Number ##.##.## RF Channel ## Network ID #### Range ### Autospan Level ## Last Cal ## Days Sensor Life ###% Temperature ##C Alarm 1 Alarm 2 Set Gas Type Set Autospan Level Set Gas Factor **Bump** Test **Restore Defaults** Set RF Channel Alarm Settings Set Modbus<sup>™</sup> ID



#### **Software Flowchart**



Figure 14 Menu Flow Chart

# 3.3 Normal Operation

In normal operation, the ITM Display will be blank and will display the gas reading once every 10 seconds for about 2 seconds (normally appear as 0). At any time swiping a magnet across either **PGM1** or **PGM2** will cause the ITM to display the units and gas type (i.e. % LEL or PPM H2S). If the sensor is actively experiencing any diagnostic faults, a swipe of the magnet will cause the display to scroll the fault condition. Refer to Section 5 Service and Maintenance for more information on fault conditions.

# 3.4 Calibration Mode

Zero and span calibration should be performed on a routine basis (quarterly minimum is advised) to ensure reliable performance. If a sensor has been exposed to any de-sensitizing gases, or to very high over-range combustible gas levels, re-calibration should be considered. Unless otherwise specified, span adjustment is recommended at 50% of the full scale range.

To enter Calibration Mode hold the magnet over PGM1 for 3 seconds. If the sensor is experiencing a fault condition the "**4**" prompt will not appear until the fault(s) have been displayed. When the ITM enters Calibration Mode the display will scroll "**Pgm1=Zero . . . Pgm2=Span**" twice before returning to Normal Mode (about 5 seconds).



#### 3.4.1 AutoZero

The AutoZero function is used to zero the sensor. AutoZero should be performed periodically or as required. AutoZero should be considered after periods of over-range target gas exposure. Local ambient air can be used to zero calibrate a combustible gas sensor as long as it can be confirmed that it contains no target or interference gasses. If this cannot be confirmed then a zero air or  $N_2$  cylinder should be used.

#### Material Requirements:

- Teledyne DetconMicroSafe<sup>™</sup> Programming Magnet (PN 327-000000-000)
- Teledyne Detcon Splash Guard with integral Cal Port (PN 613-120000-700) and Calibration Wind Guard (PN 613-120000-700) -OR-
- Teledyne Detcon Threaded Calibration Adapter (PN 943-000006-132)
- Teledyne Detcon Zero Air cal gas (PN 942-001123-000) (or use ambient air if no target gas is present)
- Teledyne Detcon Nitrogen 99.99% (PN 942-640023-100)

**NOTE:** The zero gas source may be zero air or  $N_2$  for toxic sensors, but must be pure  $N_2$  (99.99%) for  $O_2$  deficiency sensors .

**NOTE:** The Calibration Wind Guard must be used when the Splashguard Adapter with integral Cal Port is used. Failure to use the Calibration Wind Guard may result in an inaccurate AutoZero calibration.

- a) For combustible gas sensors, if the ambient air is known to contain no target gas content, then it can be used for zero calibration. If a zero gas cal cylinder is going to be used, attach the calibration adapter and set flow rate of 200-500cc/min (500cc/min is the recommended flow rate) and let sensor purge for 1 to 2 minutes before executing the **AutoZero**.
- b) From normal operation, enter calibration mode by holding the programming magnet over PGM1 for 3 seconds The display will then scroll Pgm1=Zero Pgm2=Span. Hold the programming magnet over PGM1 for 3 seconds once the "◄" prompt appears to execute AutoZero (or allow to timeout in 5 seconds if AutoZero is not desired).

NOTE: The "◄" prompt will show that the magnetic switch is activated during the 3 second hold period. NOTE: Upon entering Calibration Mode, the Modbus<sup>TM</sup> Status Register bit 14 is set to signify the sensor is in-calibration mode. This bit will remain set until the program returns to normal operation.

c) The ITM will display the following sequence of text messages as it proceeds through the AutoZero sequence:

#### Zero Cal... Setting Zero... Zero Saved (each will scroll twice)

d) Remove the zero gas and calibration adapter, if applicable.

#### 3.4.2 AutoSpan

The AutoSpan function is used to span calibrate the sensor. AutoSpan should be performed periodically or as required. AutoSpan should be considered after periods of over-range target gas exposure. Unless otherwise specified, span adjustment is recommended at 50% of range. This function is called **AUTO SPAN**.

**NOTE:** Before performing AutoSpan Calibration, verify that the AutoSpan level matches the span calibration gas concentration as described in Section 3.4.4 Set AutoSpan Level.

#### Material Requirements:

- Teledyne DetconMicroSafe<sup>™</sup> Programming Magnet (PN 327-000000-000)
- Teledyne Detcon Splash Guard with integral Cal Port (PN 613-120000-700) and Calibration Wind Guard (PN 613-120000-700) -OR-
  - Teledyne Detcon Threaded Calibration Adapter (PN 943-000006-132)
- Teledyne Detcon Span Gas. Recommended span gas is 50% of range with target gas. Other suitable span gas sources containing the target gas in air or N2 balance are acceptable.



**NOTE:** Contact Teledyne Detcon for Ordering Information on Span Gas cylinders.

**NOTE:** A target gas concentration of 50% of range is strongly recommended. This should be supplied at a controlled flow rate of 200 to 500cc/min, with 500cc/min being the recommended flow rate. Other concentrations can be used if they fall within allowable levels of 5% to 100% of range.

**NOTE:** The Calibration Wind Guard must be used when the Splashguard Adapter with integral Cal Port is used. Failure to use the Calibration Wind Guard may result in an inaccurate AutoZero calibration.

**NOTE:** It is generally not advised to use other gasses to cross-calibrate for span. Cross-calibration by use of other gasses should be confirmed by Teledyne Detcon.



*CAUTION*: Verification that the calibration gas level setting matches the calibration span gas concentration is required before executing "AutoSpan" calibration. These two numbers must be equal.

AutoSpan consists of entering calibration mode and following the menu-displayed instructions. The display will ask for the application of span gas in a specific concentration. The applied gas concentration must be equal to the calibration gas level setting. The factory default setting and recommendation for span gas concentration is 50% of range. If a span gas containing the recommended concentration is not available, other concentrations may be used as long as they fall between 5% and 95% of range. However, any alternate span gas concentration value must be programmed via the **Set AutoSpan Level** menu before proceeding with AutoSpan calibration. Follow the instructions a) through f) below for AutoSpan calibration.

- a) Verify that the AutoSpan level is equal to the calibration span gas concentration. (Refer to View Sensor Status in Section 3.4.2.) If the AutoSpan level is not equal to the calibration span gas concentration, adjust the AutoSpan level as instructed in Section 3.3.2AutoSpan.
- b) From normal operation, enter calibration mode by holding the programming magnet over **PGM1** for 3 seconds.

**NOTE:** The "◄"prompt will show that the magnetic switch is activated during the 3 second hold period.

c) The display will then scroll PGM1=Zero PGM2=Span. Hold the programming magnet over PGM2 for 3 seconds to execute AutoSpan (or allow to timeout in 5 seconds if AutoSpan is not intended). The ITM will then scroll Apply XX % Gas.

**NOTE:** Upon entering Calibration Mode, the Modbus<sup>™</sup> Status Register bit 14 is set to signify the sensor is in-calibration mode. This bit will remain set until the program returns to normal operation.

d) Apply the span calibration test gas for combustible gas sensors at a flow rate of 200-500cc/min (500cc/min is the recommended flow rate). As the sensor signal begins to increase the display will switch to flashing XX reading as the ITM shows the sensor's as found response to the span gas presented. If it fails to meet the minimum in-range signal change criteria within 2 minutes, the display will report Range Fault twice and the ITM will return to normal operation, aborting the AutoSpan sequence. The ITM will continue to report a Range Fault until a successful calibration is completed.

Assuming acceptable sensor signal change, after 1 minute the reading will auto-adjust to the programmed AutoSpan level. The ITM then reports the following messages:

#### "Remove Gas."

- e) Remove the span gas source and calibration adapter. The ITM will report a live reading as it clears toward 0. When the reading clears below 10% of range, the ITM will display **Span Complete** and will revert to normal operation. If the sensor fails to clear to less than 10% in less than 5 minutes, a **Clearing Fault** will be reported twice and the ITM will return to normal operation, aborting the AutoSpan sequence. The ITM will continue to report a **Clearing Fault** until a successful calibration is completed.
- f) AutoSpan calibration is complete.

**NOTE:** If the sensor fails the minimum signal change criteria, a **"Range Fault"** will be declared and the 'Range Fault' fault bit will be set on the Modbus<sup>™</sup> output.

**NOTE:** If the sensor fails the clearing time criteria, a "**Clearing Fault**" will be declared and the 'Clearing Fault' fault bit will be set on the Modbus<sup>TM</sup> output.



# 3.5 Program Mode

Program Mode provides a **View Sensor Status** menu to check operational and configuration parameters. Program Mode also provides for adjustment of the AutoSpan Level, Gas Factor, Gas Type and Range, and Serial ID. Additionally, Program Mode includes the diagnostic function "Bump Test" and "Restore Defaults".

The Program Mode menu items appear in the order presented below:

View Sensor Status

Set Gas Type

Set AutoSpan Level

Set Gas Factor

Bump Test

**Restore Defaults** 

Set RF Channel

Alarm Settings

Set Modbus<sup>™</sup> ID

#### 3.5.1 Navigation Program Mode

From Normal Operation, enter Program Mode by holding the magnet over PGM2 for 3 seconds. Note, the "**)**" prompt will show that the magnetic switch is activated during the 3 second hold period. If the sensor is experiencing a fault condition the "**)**" prompt will not appear until the fault(s) have been displayed. The ITM will enter Program Mode and the display will display the first menu item "**View Sensor Status**". To advance to the next menu item, hold the magnet over PGM1 or PGM2 or "**(**" for PGM1) will appear, and immediately remove the magnet. The ITM will advance to the next menu item. Repeat this process until the desired menu item is displayed. Note, PGM1 moves the menu items from right to left and PGM2 moves the menu items from left to right.

To enter a menu item, hold the magnet over PGM1 or PGM2 while the menu item is scrolling. At the conclusion of the text scroll the "**\**" prompt ("**\**" for PGM2 or "**\**" for PGM1) will appear, continue to hold the magnet over PGM1 or PGM2 for an additional 3-4 seconds to enter the selected menu item. If there is no magnet activity while the menu item text is scrolling (typically 4 repeated text scrolls), the ITM will automatically revert to Normal Operation.

#### 3.5.2 View Sensor Status

View Sensor Status displays all current configuration and operational parameters including: sensor type, software version number, detection range, AutoSpan level, days since last AutoSpan, estimated remaining sensor life, gas factor, gas type, sensor ambient temperature, and and alarm levels.

From the **View Sensor Status** text scroll, hold the magnet over PGM1 or PGM2 until the "**)**" prompt appears and continue to hold the magnet in place for an additional 3-4 seconds (until the display starts to scroll "**Status Is**"). The display will scroll the complete list of sensor status parameters sequentially:

#### Main processor firmware version

The menu item appears as: "Mp App ##.##"

#### **Co-processor firmware version**

The menu item appears as: "Cp App ##.##"

#### **Rf firmware version**

The menu item appears as: "Rf App ##.##.##"

#### **Rf Software version**

The menu item appears as: "Rf Sw ##.##"



#### Modbus ID

The menu item appears as: "Modbus ID is ##"

#### Serial Number

The menu item appears as: "Serial Number ##.###".

This is the serial number for the radio embedded in the CXT-IR.

#### RF Channel

The menu item appears as: "RF Channel ##"

#### Network ID

The menu item appears as: "Network ID ####"

#### Range

The menu item appears as: "Range ###"

#### **AutoSpan Level**

The menu item appears as: "Auto Span Level ##"

#### **Temperature Compensation Level**

The menu item appears as: "Tempcomp Level ##"

#### Last Cal

The menu item appears as: "Last Cal ## Days"

#### Sensor Life

The menu item appears as: "Sensor Life ###%"

#### Temperature

The menu item appears as: "Temperature ##C"

#### Alarm1

The menu item appears as: "Alarm1 Level ##"

```
"Ascending" or "Decending"
```

"Latching" or "NonLatching"

"Energized" or "DeEnergized"

#### Alarm2

The menu item appears as: "Alarm2 Level ##"

"Ascending" or "Decending"

"Latching" or "NonLatching"

#### "Energized" or "DeEnergized"

When the status list sequence is complete, the ITM will revert to the View Sensor Status text scroll.

The user can either:

- a) review list again by executing another 3 to 4 second hold,
- b) move to another menu item by executing a momentary hold over PGM1 or PGM2, or
- c) return to normal operation via automatic timeout of about 15 seconds (the display will scroll **View Sensor Status** four times and then return to normal operation).

#### 3.5.3 Set Gas Type

The IR sensor has a slightly different linearization requirement for different groupings of target gases.

The two selections are:

- %LEL and
- %VOL.

The Set Gas Type menu function is a simple choice between these two gas type groupings.

NOTE: The default value for Gas Type is methane (%LEL)..



The menu item appears as: Set Gas Type.

From the Set Gas Type and Range text scroll, hold the magnet over **PGM1** or **PGM2** until the arrow prompt appears and continue to hold the magnet in place for an additional 3 to 4 seconds (until the display starts to scroll **%LEL/%VOL**). Swipe the magnet momentarily over **PGM2** or **PGM1** to change the selection until the correct choice is displayed. Hold the magnet over **PGM1** or **PGM2** for 3 seconds to accept the new value. The display will scroll **Type Saved**, then **Set Range** followed by the currently selected Range. Momentarily hold the magnet over **PGM1** or **PGM1** or **PGM2** to change the Range Selection until the correct value is displayed. Hold the magnet over **PGM2** for 3 seconds to accept the new value.

Move to another menu item by executing a momentary hold, or, return to normal operation via automatic timeout of about 15 seconds (the display will scroll **Set Gas Type** 4 times and then return to normal operation).

#### 3.5.4 Set AutoSpan Level

Set AutoSpan Level is used to set the span gas concentration level that is being used to calibrate the sensor. This level is adjustable from 5% to 95% of range. The current setting can be viewed in View Program Status.

The menu item appears as: Set AutoSpan Level.

From the Set AutoSpan Level text scroll, hold the magnet over **PGM1** or **PGM2** until the arrow prompt appears and continue to hold the magnet in place for an additional 3-4 seconds (until the display starts to scroll **Set Level**). The display will switch to **XX** (where XX is the current gas level). Swipe the magnet momentarily over **PGM2** to increase or **PGM1** to decrease the AutoSpan Level until the correct level is displayed. When the correct level is achieved, hold the magnet over **PGM2** for 3 to 4 seconds to accept the new value. The display will scroll **Level Saved**, and revert to **Set AutoSpan Level** text scroll.

Move to another menu item by executing a momentary hold, or return to normal operation via automatic timeout of about 15 seconds (the display will scroll **Set AutoSpan Level** 4 times and then return to normal operation).

#### 3.5.5 Bump Test

Bump Test is used to check the response of the sensor with the indication of response limited to the display only. The results of the bump test will not affect the reading register on the Modbus<sup>TM</sup> output.

The menu item appears as: **Bump Test** 

From the Bump Test text scroll, hold the magnet over **PGM1** or **PGM2** until the arrow prompt appears and continue to hold the magnet in place for an additional 3 to 4 seconds (until the display starts to scroll **Bump Test Started**).

The display will return to normal operation alternating between the live gas reading and showing **Bump** until 2 minutes expires or the execution of a momentary hold over **PGM1** or **PGM2**, when the display will scroll **Bump Test Ended**.

#### **3.5.6** Restore Defaults

The CXT-IR sensor has the option to restore its internal memory settings to factory default conditions.

The menu item appears as: Restore Defaults.

**NOTE:** Restoring factory defaults should only be used when absolutely necessary. All previously existing configuration inputs will have to be re-entered if this function is executed. A full 10-second magnet hold on PGM 2 is required to execute this function.

From the Restore Defaults text scroll, hold the magnet over **PGM2** until the arrow prompt appears and continue to hold the magnet in place for an additional 3 to 4 seconds (until the display starts to scroll **Defaults Restored**). The display will then revert to **Restore Defaults** text scroll.

Move to another menu item by executing a momentary hold, or, return to normal operation via automatic timeout of about 15 seconds (the display will scroll **Restore Defaults** four times and then return to normal operation).



*CAUTION*: After the defaults are restored, the sensor must be recalibrated.



#### 3.5.7 Set RF Channel

The CXT-IR sensor communicates wirelessly and can be set to use unique wireless radio channel. Set RF Channel is used to set the RF radio channel. It is adjustable from 0 to 15.

The menu item appears as: Set RF Channel.

From the Set RF Channel text scroll, hold the programming magnet over **PGM1** or **PGM2** until the arrow prompt appears and continue to hold the magnet in place for an additional 3 to 4 seconds (until the display starts to scroll Set Channel). The display will then switch to **XX** (where XX is the current RF channel). Swipe the magnet momentarily over **PGM2** to increase or **PGM1** to decrease the hexadecimal number until the desired ID is displayed. Hold the magnet over **PGM2** for 3 to 4 seconds to accept the new value. The display will scroll **Channel Saved**, and revert to **Set RF Channel** text scroll.

Move to another menu item by executing a momentary hold, or, return to Normal Operation via automatic timeout of about 15 seconds (the display will scroll **Set RF Channel** four times and then return to Normal Operation).

#### 3.5.8 Alarm Settings

The Alarm Settings are not used during normal operation of the unit at this time. These settings should be ignored and bypassed.

The menu item appears as: "Alarm Settings". At the conclusion of the text scroll the ") "prompt (")" for PGM2 or "(" for PGM1) will appear, continue to hold the magnet over PGM1 or PGM2 for an additional 3-4 seconds to move to either the next or prior menu selection. If there is no magnet activity while the menu item text is scrolling (typically 4 repeated text scrolls), the ITM will automatically revert to Normal Operation.

#### 3.5.9 Set Modbus ID

Teledyne Detcon CXT sensor can be polled serially via Modbus<sup>™</sup> RTU. Refer to Section 4.0 for details on using the Modbus<sup>™</sup> output feature.

Set Modbus ID is used to set the Modbus<sup>™</sup> address of the unit. It is adjustable from 01 to 256 in hexadecimal format (01-FF hex). Each sensor must have a unique Modbus address to operate correctly on the network. The current serial ID can be viewed in View Sensor Status.

The menu item appears as: "Set Serial ID".

From the "Set Modbus ID" text scroll, hold the programming magnet over PGM1 or PGM2 until the ")" prompt appears and continue to hold the magnet in place for an additional 3-4 seconds (until the display starts to scroll "Set ID"). The display will then switch to "XX" (where XX is the current ID address). Swipe the magnet momentarily over PGM2 to increase or PGM1 to decrease the hexadecimal number until the desired ID is displayed. Hold the magnet over PGM2 for 3-4 seconds to accept the new value. The display will scroll "ID Saved", and revert to "Set Modbus ID" text scroll.

Move to another menu item by executing a momentary hold, or, return to Normal Operation via automatic timeout of about 15 seconds (the display will scroll "Set Serial ID" 5 times and then return to Normal Operation).

### **3.6 Fault Diagnostic/Failsafe Feature**

If the ITM should incur a fault, the Global Fault bit will be set on the Modbus<sup>™</sup> output. This can occur if the ITM detects a problem with the sensor, detects that there is no sensor connected, if the ITM has an internal fault, or other fault condition. The Global Fault bit will be set on the Modbus<sup>™</sup> output until the problem is resolved. The display will show the Fault when a magnetic programming tool is swiped across either PGM1 or PGM2. The error codes are defined in Section 6 Troubleshooting Guide.



# 4. Modbus<sup>TM</sup> Communications

Modbus<sup>TM</sup> communication with a CXT Sensor is normally accomplished using another wireless transceiver such as the RXT-320 which is connected through a RS-485 interface to a Modbus<sup>TM</sup> master control unit. The control unit can then access the Modbus<sup>TM</sup> registers within the CXT to obtain readings and status of the sensor.

As with normal Modbus<sup>TM</sup> operation, there can be only one Modbus<sup>TM</sup> master that polls all the other devices on the network which are considered Modbus<sup>TM</sup> slaves. Each sensor must have a unique Modbus<sup>TM</sup> address and be on the same RF channel (for communication) to work properly on the wireless network. Both the Modbus<sup>TM</sup> ID and the RF channel are set on the CXT sensor using the display.

The Modbus<sup>TM</sup> master control unit with RXT-320 transceiver (or equivalent) is responsible for broadcasting requests and receiving slave device responses. The CXT sensor receives these requests through its own internal transceiver and responds if the Modbus<sup>TM</sup> address and proper register set matches. The response will be received by the RXT-320 and presented to the master control unit across the RS-485 interface.

# 4.1 General Modbus<sup>TM</sup> Description

The Modbus<sup>TM</sup> communication uses the RTU transmission mode per the Modbus<sup>TM</sup> specification. The basic frame format for Modbus<sup>TM</sup> consists of a Modbus<sup>TM</sup> address, function code, data and CRC.

Address Field	Function Code	Data	CRC
Figure 15 Modbus™ Frame Format			

The Modbus<sup>™</sup> ID Field is the unique Modbus<sup>™</sup> address of each device on the network. The Function Code is the function to be performed. The Data contains read or write data and is formatted according to the function being performed. The CRC (Cyclic Redundancy Code) is used to detect errors in the frame. Frames with errors are invalid and ignored.

Modbus<sup>TM</sup> transactions consist of both a request by the controller and response from the device being addressed so there are two frames transferred for every transaction. Every request is evaluated by the CXT to determine if it is addressed to it, and if it falls within the register address range. If these two conditions are true, the CXT will then check to see if it is a valid Function Code. Function Codes supported by the CXT are:

Function Code 03 (03h) – Read Holding Registers

Function Code 06 (06h) - Write Single Register

Function Code 16 (10h) – Write Multiple Registers

If an invalid function code is performed, the CXT will ignore the request by default and the controller will timeout and continue with the next transaction.

### 4.1.1 Modbus<sup>TM</sup> Exceptions

The CXT is capable of returning Modbus<sup>™</sup> exceptions when it cannot service a Modbus<sup>™</sup> request meant for that CXT. By default this is turned off since it can cause issues with some controllers that do not process Modbus<sup>™</sup> exceptions (See Section 4.2.2.4 Register – Control). The following exception codes are supported and returned when Modbus<sup>™</sup> exceptions are enabled:

Exception Code	Name	Meaning
01	Illegal Function	Unsupported function code. Only 03, 06 and 16 are supported.
02	Invalid register address detected. If any request for r           Illegal Data Address         outside of the valid register address for the CXT occu           exception code will be returned.	

 Table 1 Exception Codes

There are other exception codes defined in Modbus<sup>™</sup> but these are the only ones used by the CXT.

NOTE: When using Teledyne Detcon controllers, Modbus exceptions should be turned off.



### 4.1.2 Modbus<sup>TM</sup> Broadcast Request

The Modbus<sup>TM</sup> broadcast request was introduced in the CXT to support commands to be executed across all CXT transceivers simultaneously. More specifically this is used to place all CXTs in a low power state for a specified time to conserve battery life. Only the transceivers (radio) are placed into a low power state, the CXT sensor will continue to operate normally. If none of the CXTs are battery powered then there is no need to issue a command to place the transceivers in low power mode.

According to the Modbus<sup>TM</sup> specification a broadcast request is defined as a request with the Address Field set to 0 and is used for writing only. There is no response returned as with normal Modbus<sup>TM</sup> transactions since all devices on the system are accessed at the same time. Both Function Codes 06 and 16 (writes) are supported with a broadcast request on the CXT.

Since there is no response on the broadcast request, there is a requirement to wait for a period of time before sending out the next request. This allows all slave devices to process the command before the next request is received. This is defined as the "turnaround delay". This turnaround delay should be approximately 150 milliseconds for broadcast requests sent to the CXT. Controllers in general can meet this timing because it takes longer than this to generate the next request so it may be unnecessary to make any adjustments to meet this timing.

**NOTE:** Controllers that generate Modbus<sup>™</sup> broadcast requests to the CXT must ensure a turnaround delay of 150ms is met otherwise the next request can cause the broadcast request to be overwritten and ignored.

Broadcast requests are not confined to commands to put the network in low power mode, but can be used where any normal write command is used.

# 4.2 Modbus<sup>TM</sup> Register Map and Description

When the CXT is assigned a Modbus<sup>TM</sup> address, the following registers become available to the controller for access. All CXT sensors implement this register set. Some registers are Read Only (R) and others are Read/Write (R/W) as shown by the R/W column. This equates to specific function codes where Read is function code 03 and Write is function code 06 or 16.

**NOTE:** A write to a Read Only register is allowed and returns a response, but it does not change the value of the register. In some devices this would return an exception code

The register map (Table 3) for the CXT sensor gives a brief description for each register or register set. This information is only meant as a reference. The registers are divided into two sections, one for the CXT sensor and the other for the CXT transceiver. For a more detailed description of the Register Map please contact Teledyne Detcon.

Offset	Name	R/W	Comment
0000	CXT-IR-100 Device Type	R	= 36
0001	Range	R/W	Detectable Range
0002	Reading	R	Current Gas Reading
0003	Calibration Level	R/W	Auto Span Level
0004	Life	R	Sensor Life
0005	Sensor Faults	R	Fault bits
0006	Sensor Model	R	DM (set to 1)
0007	Days since Calibration	R	
0008	Reserved	R	
0009	Reserved	R	
0010	Sensor Temperature	R	
0011	DECIMAL	R/W	
0012	Temperature Compensation	R/W	
0013	Reserved	R	
0014	COUNTS	R/W	

CXT-IR Instruction Manual

Offset	Name	R/W	Comment	
0015	CONTROL	R/W		
0016	String	R	Set during production/test	
0017	String	R	Set during production/test	
0018	String	R	Set during production/test	
0019	String	R	Set during production/test	
0020	String	R	Set during production/test	
0021	String	R	Set during production/test	
0022	Reserved	R/W	NOT USED	
0023	Sensor Controller Version	R	Year.Week	
0024	Reserved	R		
0025	Reserved	R		
0026	Reserved	R		
0027	Wireless Controller Version	R	Major.Minor	
0028	Reserved	R		
0029	Radio Firmware Version	R	00.Major	
0030	Radio Firmware Version	R	Minor.Build	
0031	Radio Software Version	R	Major.Minor	
0032	Wireless ID High	R	00.XX	
0033	Wireless ID Low	R	XX.XX	
0034	RF Channel	R	Wireless RF Channel (Set in Display)	
0035	Network ID	R	Defaults to RF Channel (Set in Display)	
0036	Modbus Address	R	CXT Modbus Address (Set in Display)	
	RXT-320 Compatibl	e Register	rs for Wireless Transceiver	
8192	RXT-320 Device Type	R	22 (for compatibility)	
8193	Reserved			
8194	Reserved			
8195	Reserved			
8196	Reserved			
8197	Reserved			
8198	Reserved			
8199	Battery Life in Percent	R	Smart Battery Life remaining in percent	
8200	Battery Life in Minute	R	Smart Battery Life remaining in minutes	
8201	Wireless Controller Version	R	same as register 0027	
8202	RF Update Rate	W	Number of seconds to power down transceiver	
8203	Control	R/W	Wireless Control	
8204	Status	R	Wireless Status	
8205	Input Voltage	R	Smart Battery voltage or Input Voltage to A/D	
8206	Battery Error Count	R/W	Smart Battery read error count if detected	
8207	Reserved			
8208	Timestamp[0]	R	Time since power applied Seconds High	
8209	Timestamp[1]	R	Time since power applied Seconds Low	
8210	Timestamp[2]	R	Time since power applied Milliseconds	

### 4.2.1 CXT Sensor Registers

### 4.2.1.1 Sensor Faults – Register 0005

The sensor fault status register consists of High and Low Status Bits. These bits are set/reset as faults occur or are cleared. Each bit has a particular meaning:

Register #	High Byte	Low Byte
0005	Status Bits	Status Bits

Bits read as 0 are FALSE; bits read as 1 are TRUE CXT-IR Instruction Manual



- Status Bits High Byte:
- Bit 15 Reserved
- Bit 14 Calibration Mode
- Bit 13 Reserved
- Bit 12 Zero Fault
- Bit 11 Range Fault
- Bit 10 Reserved
- Bit 9 Clearing Fault
- Bit 8 Reserved
- Status Bits Low Byte:
- Bit 7 Sensor Fault
- Bit 6 Processor Fault
- Bit 5 Memory Fault
- Bit 4 Reserved
- Bit 3 Reserved
- Bit 2 Temperature Fault
- Bit 1 Auto Span Fault
- Bit 0 Global Fault

#### 4.2.2 CXT Transceiver Registers

#### 4.2.2.1 Battery Info – Multiple Register

If a Teledyne Detcon smart battery pack is connected to the CXT, there are five registers associated with information about that battery. The CXT utilizes the I<sup>2</sup>C interface to read battery status and only one Teledyne Detcon battery pack can be read per CXT.

The controller can determine if a battery is present by reading the Status Register (register 8204). There are two bits in this sixteen bit register pertaining to the battery, Battery Detect – bit 4 (lowest bit is 0) and Battery Fault – bit 5. Both bits default to a value of 0. Battery Detect will be set once the first read of the battery over the  $I^2C$  interface was successful. Battery Fault will be set if a battery was detected but the last read failed. Battery Fault is re-evaluated upon every read of the battery which is set to approximately every 5 seconds. Register 8206 ( $I^2C$  Batt Read Fails) will increment by 4 each time there is a failure since there are 4 attempts before declaring failure. This register can be cleared by writing a 0 to it at any point.

Once the battery has been detected the controller can read the battery life (registers 8199 and 8200). The battery adjusts these values based upon the average current usage. If this usage varies widely over time it will take some time to re-adjust the battery life readings. For instance an Alarm Station with no alarms will consume a very small amount of battery but when Alarms are active this will jump to a much higher level of usage. So in this case battery life may go from several weeks down to several hours.

The battery life is presented in two forms, life remaining in percentage (register 8199) and life remaining in minutes (register 8200). The battery Life remaining is percentage is a value between 0 and 100 and battery life in minutes is an unsigned value between 0 and 65535. Both readings are generally necessary to provide appropriate feedback to the user. Life in minutes is the best for determining when to change the battery. For example if the user wanted to be notified a day before the battery needed to be changed, the user could set a threshold in the controller to be notified of low battery after 1440 minutes (1 day).

Since 65535 is the maximum value for life remaining in minutes, this represents a maximum of 45.5 days. The battery life for an application can be much greater than this value and will remain at a reading of 65535 until it drops below this. Life in percentage was added for this reason. Percentage will track starting at 100 percent and drop down as battery life decreases. The controller can therefore use both registers, one to represent usage in percentage to present to the user and then use the life in minutes to set a threshold on when a low battery condition exists for changing the battery.

#### **4.2.2.2** Wireless Controller Version

This is set to a value based upon the version of firmware programmed into the RXT-320 microcontroller. It is stored as two byte value representing the major and minor revision numbers. So a 0113h (275 decimal) represents a major version of 01 and minor version of 13. As software is updated this will be incremented appropriately.



#### 4.2.2.3 Register – Update Rate

The Update Rate represents the amount of time in seconds the CXT transceiver will be in a low power state. Its main purpose is to provide a mechanism to place all wireless transceivers in a system into a low power mode to conserve battery power. If there are no batteries used within the network of wireless transceivers this register would not be utilized.

Upon power up, this register is set to 0 and the CXT transceiver is not in low power mode. To place a network to low power mode the controller will generate a broadcast request (Modbus<sup>TM</sup> address = 0) and do a single write (function code 06) to register 8202 with the number of seconds the network should go into low power mode. During low power mode, there can be no access to any device on the network so changes in sensor readings will not be updated. Once a non-zero value is written to this register on all transceivers, they will begin counting down until the Update Rate register reaches zero, at which time all transceivers should be active again and ready for network communication. The controller will monitor the update rate time remaining by accessing Update Rate register on the RXT-320 (or equivalent) that it is attached to it. The Modbus<sup>TM</sup> interface remains active, only the wireless network is placed in a low power state. The value of this register can be between 0 and 65535 which allows a maximum low power time of 18.2 hours. Removal of power will reset Update Rate to 0 and the transceiver will be active again.

#### 4.2.2.4 Register – Control

The CXT transceiver control register is generally unused and should not be written to normally. Using the control register, the CXT can be reset and Modbus<sup>TM</sup> exceptions can be enabled. Each bit in the control register can control a particular function and should be read first then modify the bits needed and written back. The default state of the register is 0. All reserved bits should always be set to a 0 when writing. The listing below shows the bit assignments.

Bit 15:	Reserved (set to 0)
Bit 14:	Reserved (set to 0)
Bit 13 – 12:	Reserved (set to 0)
Bit 11:	Modbus Exceptions Enabled
Bit 10 – 08:	Reserved (set to 0)
Bit 07:	Reset the microcontroller and wireless radio
Bit 06:	Reset the microcontroller
Bit 05 – 00:	Reserved (set to 0)

#### 4.2.2.5 Register – Status

This register contains status of the CXT transceiver and some of the bits have already been covered in the battery description. These default to 0 upon reset. The bit assignment and description are given below.

Bit 15 – 08:	Reserved (set to 0)
Bit 07:	Reserved (set to 0)
Bit 06:	Reserved (set to 1)
Bit 05:	I2C Fault on last read of Battery Status
Bit 04:	Battery Detected
Bit 03:	Reserved (set to 0)
Bit 02:	Reserved (set to 1)
Bit 01:	Reserved (set to 0)
Bit 00:	Reserved (set to 0)

#### 4.2.2.6 Register – Timestamp

Three registers are utilized to maintain a timestamp that increments on the microcontroller after power up. These are all set to 0 upon power up or a microcontroller reset. The first two registers 8208 and 8209 are internally combined into a single 32 bit register and incremented each second. The last register 8210 maintains the millisecond count and will count from 0 to 999 and start over again.



# 5. Service and Maintenance

# 5.1 Calibration Frequency

In most applications, monthly to quarterly span calibration intervals will assure reliable detection. However, industrial environments differ. Upon initial installation and commissioning, close frequency tests should be performed, weekly to monthly. Test results should be recorded and reviewed to determine a suitable calibration interval.

# 5.2 Visual Inspection

The Sensor should be inspected annually:

- Inspect the sensor for signs of corrosion, pitting, and water damage.
- Remove the Splash Guard and inspected it for blockage, broken, cracked, or missing pieces.
- For H2S Sensor assemblies, inspect CXT-IR Series Splashguard Adapter Assembly with integral filter (P/N 602-003552-100) for blockage of filter material.
- Inspect inside of the Junction Box for signs of water accumulation, signs of corrosion.
- Check wiring to ensure there are no loose or pinched wires and all connections are clean and tight.

# **5.3** Condensation Prevention Packet

A moisture condensation packet should be installed in every explosion proof Junction Box. The moisture condensation prevention packet will prevent the internal volume of the J-Box from condensing and accumulating moisture due to day-night humidity changes. This packet provides a critical function and should be replaced annually. Teledyne Detcon's PN is 960-202200-000.

# 5.4 Replacement of batteries/battery pack

### 5.4.1 Units with 12V Smart Battery Pack

The CXT-IR Sensor incorporates a 'Low battery' fault message which will appear as an alternating display between the current gas reading and 'VOLT' on the sensor display. This fault will appear when the battery voltage drops below 7.5 volts. When the voltages drops below 7.2 volts the display will change to a steady 'VOLT' display, the sensor will then enter into 'Fault' mode, and the sensor will no longer provide a valid gas reading.

**NOTE:** The safety approvals require removing entire sensor assembly to a non-hazardous area before installing or changing out the batteries or battery pack.

- 1. Remove the cover from the J-box.
- 2. Unscrew battery bracket lid, and swing the lid away from the battery pack.
- 3. Remove the battery pack from the J-box, and replace with new battery pack.
- 4. Swing the lid back over the battery pack, and re-tighten screws in battery bracket lid.
- 5. Replace the cover on the J-box.

#### 5.4.2 Units with D-size Non-Rechargeable Batteries

**NOTE:** The safety approvals require removing entire sensor assembly to a non-hazardous area before installing or changing out the batteries or battery pack.

- 1. Remove the cover from the J-box.
- 2. Unscrew battery bracket lid, and swing the lid away from the battery pack.
- 3. Remove the battery holder from the J-box.
- 4. Loosen the four 4-40 Philips Head Screws from the bottom of the battery pack. It is not necessary to remove the screws, they are captive head screws, and will not fall out of the assembly.
- 5. The orientation of batteries is marked on the inside of the cover and the holder. Remove the batteries from the battery holder.



- 6. Replace the batteries with the same type (Teledyne Detcon P/N 360-TL5930-000). Pay close attention to the orientation of the batteries. Installing the batteries incorrectly can cause damage to the batteries, the battery holder and the unit (refer to Figure 19). It is permissible to use only Tadiran Model TL-5930 batteries. Do NOT use regular 'D' size batteries, as this may cause damage to the sensor assembly.
- 7. Reinstall the bottom cover of the battery housing, and tighten the four 4-40 philips head screws to reassemble the battery holder.
- 8. Swing the lid back over the battery pack, and re-tighten screws in battery bracket lid.
- 9. Replace the cover on the J-box.



Figure 16 Battery Orientation Diagram

# 5.5 Replacement of Plug-in Sensor

**NOTE:** It is not necessary to remove power while changing the plug-in combustible gas sensor in order to maintain area classification, since it is intrinsically safe.

**NOTE:** Only replace the plug-in sensor with an authorized CXT-IR family of gas sensors.



Figure 17 Sensor Cell and ITM Mating



- 1. Use a 1/16" Allen wrench to release the locking setscrew that locks the ITM and splashguard adapter assembly together (One turn only Do not remove setscrew completely).
- 2. Remove the splashguard.
- 3. Unthread and remove the splashguard adapter assembly from the ITM.
- 4. Gently pull the plug-in sensor out of the ITM. Verify the gas type and range of the new sensor cell is correct.
- 5. Orient the new plug-in sensor so that it matches with the female connector pins. When properly aligned, press the sensor in firmly to make the proper connection.
- 6. Thread the splashguard adapter assembly onto the ITM to a snug fit and tighten the locking setscrew using the 1/16" Allen wrench.
- 7. Install the splashguard.
- 8. Check and perform zero calibration and span calibration as per Section 3.3.

# 5.6 Replacement of ITM – Aluminum Junction Box

- 1. Remove the power source to the sensor assembly.
- 2. Remove the battery pack from the J-box.
- 3. Disconnect all sensor wire connections at the Junction Box Terminal Board, taking note of the wire connections, and disconnect the RF cable connector.

**NOTE:** It is necessary to remove power to the Junction box while changing the ITM in order to maintain area classification.

- 4. Use a wrench and the wrench flats provided at the top section of the ITM and unthread the ITM for removal.
- 5. Use a 1/8" Allen wrench to release the locking cap head screw that locks the ITM and splashguard adapter assembly together (One turn only Do not remove setscrew completely).
- 6. Unthread and remove the splashguard adapter assembly and splashguard from the ITM. These will be re-used with the new ITM.
- 7. Gently remove the plug-in combustible gas sensor from the old ITM and install it in the new ITM. Orient the plug-in sensor pins so that it matches the female connector pins on the new ITM then press the sensor in firmly to make proper connection.
- 8. Thread the splashguard adapter assembly onto the new ITM until snug, tighten the locking cap head screw and reinstall splashguard.
- 9. Feed the sensor assembly wires and RF cable through the <sup>3</sup>/<sub>4</sub>" female NPT port and thread the assembly into the J-box until tight and the ITM faces toward the front access point. Use the locking nut to secure the ITM in this position.
- 10. Re-connect the sensor assembly wires to the terminal board inside the Junction Box.
- 11. Re-connect the RF cable to the antenna cable.
- 12. Install the battery pack.
- 13. Check and/or perform Zero Calibration and Span Calibration in accordance with Section 3.3.



# 6. Troubleshooting Guide

If the ITM detects any functional errors the ITM will display the fault. If the sensor is experiencing a fault condition a momentary swipe of the magnet will cause the ITM to scroll the fault condition(s) across the display before the  $\blacktriangleleft$  or  $\triangleright$  prompt will appear.

#### The Display Error Codes are:

Auto Span Fault Temperature Fault Memory Fault Processor Fault Clearing Fault Range Fault Missing Sensor Cell Fault Sensor Fault Zero Fault Low Battery Fault

Some faults are self-explanatory, and if these faults occur and cannot be cleared the ITM should be replaced first to see if the fault will clear. Other faults may need further investigation. Some of the sensor problems, associated error codes, and resolutions are listed below.

#### **Missing Sensor Cell Fault**

Probable Cause: The sensor cell is not installed, is installed incorrectly, or is nonoperational.

• Replace the Sensor Cell with a known good Sensor Cell.

#### Sensor Fault

Probable Cause: The sensor optics have become too dirty to support functionality.

• Replace the Sensor Cell with a known good Sensor Cell.

#### **Under-Range problems**

Probable Cause: Sensor baseline drifted lower, interference gases,

- Perform zero calibration.
- Use zero air or N<sub>2</sub> source. (Section3.3.1AutoZero)
- Allow more time for zero stabilization if this is a biased sensor type.
- Execute successful span calibration. (Section 3.3.2AutoSpan)
- Replace plug-in combustible sensor if error continues.

#### **Stability problems**

Probable Causes: Failed sensor, empty or close to empty cal gas cylinder, problems with cal gas and delivery

- Check validity of span gas using pull tube or other means (check MFG date on cal gas cylinder).
- Use proper cal gas regulators and tubing for highly corrosive gases.
- If using Splashguard with Integral Cal Port, must use Calibration Wind Guard or air movement can compromise span gas delivery.
- Check for obstructions affecting cal gas hitting sensor face (including being wet, blocked, or corroded). Sensor assemblies use CXT-IR series splashguard adapter assembly with integral filter. Clean or replace if necessary.
- Replace the plug-in combustible sensor.

#### **Clearing problem**

Probable Causes: Failed sensor, cal gas not removed at appropriate time, problems with cal gas and delivery, background of target gas.



- The sensor must recover to < 10% of range in < 5 min after Span calibration is complete
- Use bottled air (zero air or N<sub>2</sub>) if there is a known continuous background level.
- Check validity of span gas using pull tube or other means (check MFG date on cal gas cylinder).
- Use proper cal gas regulators and tubing for highly corrosive gases
- Check for obstructions affecting cal gas hitting sensor face (including being wet, blocked, or corroded). Sensor assemblies use CXT-IR series splashguard adapter assembly with integral filter. Clean or replace if necessary.
- Replace the plug-in combustible sensor.

#### **Poor Calibration Repeatability**

Probable Causes: Failed sensor, use of wrong cal gas or problems with cal gas and delivery, interference gases.

- Check validity of span gas with regulator and sample tubing in place using pull tube or other means (check MFG date on cal gas cylinder).
- Use proper cal gas regulators and tubing for highly corrosive gases (HF, HCI, Cl2, NH3, HBR, F2, etc.)
- Check for obstructions affecting cal gas hitting sensor face (including being wet, blocked, or corroded). Sensor assemblies use CXT-IR series splashguard adapter assembly with integral filter. Clean or replace if necessary.
- Replace the plug-in combustible sensor.

#### Unstable Output/ sudden spiking

Possible Causes: Unstable power supply, inadequate grounding, or inadequate RFI protection.

- Verify power source is stable.
- Verify field wiring is properly shielded and grounded.
- Contact Teledyne Detcon to optimize shielding and grounding.
- Add Teledyne Detcon's RFI Protection Circuit accessory if problem is proven RFI induced.

#### Nuisance Alarms

- Check condulet for accumulated water and abnormal corrosion on terminal board.
- If nuisance alarms are happening at night, suspect condensation in condulet.
- Add or replace Teledyne Detcon's Condensation Prevention Packet (PN 960-202200-000).
- Investigate the presence of other target gases that are causing cross-interference signals.
- Determine if cause is RFI induced.

#### Transmitter not responding

- Verify condulet has no accumulated water or abnormal corrosion.
- Verify required batteries are installed and have enough charge to power the sensor.
- Swap with a known-good ITM to determine if ITM is faulty.

#### Low Battery / Low Voltage Fault

Possible Cause: Lithium Ion batteries are depleted.

• Change out all three of the Lithium Ion non-rechargeable 'C' size batteries with new batteries.

**NOTE:** Contact the Teledyne Detcon Service Department for further troubleshooting assistance at 281-367-4100.



# 7. Customer Support and Service Policy

#### **Teledyne Detcon Headquarters**

*Shipping Address*: 14880 Skinner Road, Cypress Texas 77429 *Phone*: 713.559.9200

- www.teledynegasandflamedetection.com
- Teledyne Detcon-service@Teledyne Detcon.com
- <u>Teledyne Detcon-sales@Teledyne Detcon.com</u>

All Technical Service and Repair activities should be handled by the Teledyne Detcon Service Department by phone or email through the contact information given above. RMA numbers should be obtained from the Teledyne Detcon Service Department prior to equipment being returned. For on-line technical service, customers should have ready the model number, part number, and serial number of product(s) in question.

All Sales activities (including spare parts purchase) should be handled by the Teledyne Detcon Sales Department via phone or email at contact information given above.

#### Warranty Notice

Teledyne Detcon Inc. warrants the Model CXT-IR gas sensor to be free from defects in workmanship of material under normal use and service for one year from the date of shipment on the transmitter electronics. See Warranty details in Section 8 CXT-IR Sensor Warranty.

Teledyne Detcon Inc. will repair or replace without charge any such equipment found to be defective during the warranty period. Full determination of the nature of, and responsibility for, defective or damaged equipment will be made by Teledyne Detcon Inc. personnel.

Defective or damaged equipment must be shipped to the Teledyne Detcon Inc. factory or representative from which the original shipment was made. In all cases, this warranty is limited to the cost of the equipment supplied by Teledyne Detcon Inc. The customer will assume all liability for the misuse of this equipment by its employees or other contracted personnel.

All warranties are contingent upon the proper use in the application for which the product was intended and does not cover products which have been modified or repaired without Teledyne Detcon Inc. approval, or which have been subjected to neglect, accident, improper installation or application, or on which the original identification marks have been removed or altered.

Except for the express warranty stated above, Teledyne Detcon Inc. disclaims all warranties with regard to the products sold. Including all implied warranties of merchantability and fitness and the express warranties stated herein are in lieu of all obligations or liabilities on the part of Teledyne Detcon Inc. for damages including, but not limited to, consequential damages arising out of, or in connection with, the performance of the product.



# 8. CXT-IR Sensor Warranty

Teledyne Detcon, Inc., as the manufacturer, warrants under intended normal use each new CXT-IR sensor to be free from defects in material and workmanship for a period of one year from the date of shipment to the original purchaser. Should the sensor fail to perform in accordance with published specifications within the warranty period, return to Teledyne Detcon, Inc., for necessary repair or replacement. All warranties and service policies are FOB the Teledyne Detcon facility located in Cypress, Texas.

#### Terms & Conditions

- The original serial number must be legible on each sensor element base.
- Shipping point is FOB the Teledyne Detcon factory.
- Net payment is due within 30 days of invoice.
- Teledyne Detcon, Inc. reserves the right to refund the original purchase price in lieu of sensor replacement.

#### **ITM Electronics Warranty**

Teledyne Detcon Inc. warrants, under intended normal use, each new Compact Wireless Sensor ITM to be free from defects in material and workmanship for a period of one year from the date of shipment to the original purchaser. All warranties and service policies are FOB the Teledyne Detcon facility located in Cypress, Texas.

Terms & Conditions

- The original serial number must be legible on each ITM.
- Shipping point is FOB the Teledyne Detcon factory.
- Net payment is due within 30 days of invoice.

Teledyne Detcon, Inc. reserves the right to refund the original purchase price in lieu of ITM replacement.

# 9. Appendix

# 9.1 Specifications

#### **System Specifications**

Sensor	Type:

**RFI/EMI** Protection:

Sensor Life:
Measuring Ranges:
Accuracy/ Repeatability:
Response Time:
Electrical Classification:
(CXT-IR)

System Specifications	
Sensor Type:	Continuous diffusion/adsorption type
	NDIR Non-Disperse Infrared
	Sub-miniature plug-in replaceable type
Sensor Life:	5 years typical
Measuring Ranges:	0-100% LEL, 0-100% by volume
Accuracy/ Repeatability:	± 3% LEL in 0-50% LEL range, ± 5% LEL in 51-100% LEL range
Response Time:	T50 < 10 seconds, $T90 < 30$ seconds
Electrical Classification:	Explosion proof
(CXT-IR)	Canada and US (NRTL)
	Class I, Division 1, Groups C and D (Tamb = $-40^{\circ}$ C to $+60^{\circ}$ C)
	Class I, Zone 1, Group IIB
	ATEX/IECEx
	Ex d ib IIB T4 Gb (Tamb = $-40^{\circ}$ C to $+60^{\circ}$ C)
	SIRA 14ATEX1034X
	EN IEC 60079-0:2018, EN 60079-1:2014, EN 60079-11:2012
Warranty:	Electronics – 1 year
<b>Environmental Specifications</b>	
Operating Temperature:	-40°C to +60°C (extended temperature model)
	-10°C to +50°C (standard temperature model)
Storage Temperature:	-35°C to +55°C typical
Operating Humidity:	10-95% RH Continuous Duty
	0-100% RH Short-Term Duration Only
Operating Pressure:	Ambient $\pm 10\%$
Air Velocity:	0-5 meters/second
<b>Electrical Specifications</b>	
Input Voltage:	7.2-30VDC
Power Consumption:	25mW (Low Power Mode)
	100mW (Typical)
	5W (With Strobe Active)

**Mechanical Specifications (ITM Only)** 

Length:	ITM - 5.165 inches (131 mm), 8.5 inches (215mm) with Splash Guard
Width:	2.2 inches (55 mm)
Weight:	2.5 lbs (1.2 Kg)
Mechanical Connection:	<sup>3</sup> / <sub>4</sub> " Male NPT threaded connection with locking nut
Electrical Connection:	four 18 gauge wire leads - 5.5" long with RF Cable terminated at SMA

Complies with EN61326



# 9.2 Spare Parts, Sensor Accessories, Calibration Equipment

Table 3 Spare Parts, Sensor	Accessories, and Calibration Equipment

Part Number	Spare Parts	
92C-IR0200-000	CXT-IR Intelligent Transmitter Module	
371-IR1II1-000	Replacement Plug-in sensor	
371-IR1II1-EXD	Replacement Plug-in sensor extended temperature range	
500-005180-100	CXT Smart Battery Terminal Board	
976-0BP303-012	Plug-in Battery Pack 12V 2200mAh (rechargeable)	
976-0BP303-290	Plug-in Battery Pack 12V 2900mAh (rechargeable)	
360-TL5930-000	Battery, Lithium 3.6V 'D'-size (Not Rechargeable)	
960-202200-000	Condensation prevention packet (for condulet, replace annually)	
602-004402-000	D-size Battery Holder (for Lithium 3.6V non-rechargeable 'D' size)	
Sensor Accessories		
6130	Sensor Rain Shield	
602-003803-100	CXT-IR Splashguard Adapter Assembly	
327-000000-000	Programming Magnet	
Calibration Accessories		
943-000006-132	Threaded Calibration Adapter	
943-050000-132	Span Gas Kit: Includes calibration adapter, span gas humidifier,	
	500cc/min fixed flow regulator, and carrying case (gas not included)	
See Detcon	Span Gases – Various	
943-05AM00-000	500cc/min Fixed Flow Regulator for Span Gas Bottle	

# **10.Revision Log**

Revision	Date	Changes made	Approval
1.0	05/18/12	Initial Release	LU
1.1	12/04/12	Adding note requiring removal of sensor assembly to non-	BM
		hazardous location to install or replace batteries	
1.2	02/20/13	Corrected title page, updated spare parts list, drawings	LU
1.3	07/19/13	Updates for battery and sensor cell faults	BM
1.4	01/20/14	Add Calibration Wind Guard to Calibration Procedures	BM
1.5	02/10/14	Add detail to battery installation	BM
1.6	02/10/14	Added Section 2.1, Updated Approvals Label	BM
1.7	09/08/14	Section 2.1, Updated Approvals Label	BM
1.8	11/27/14	Added CXT w/Strobe	LU
2.0	12/11/15	Updated to add D Cell, remove Group B gases	MM
2.1	12/11/19	Updated Company Information	MM
2.2	06/03/20	Updated approvals label, Removed gas factor table	KM
2.3	10/22/20	Updated approvals label, update company address	KM
2.4	03/10/22	Updated labels and certification references, removed references to	KM
		discontinued C-cell battery configuration	



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