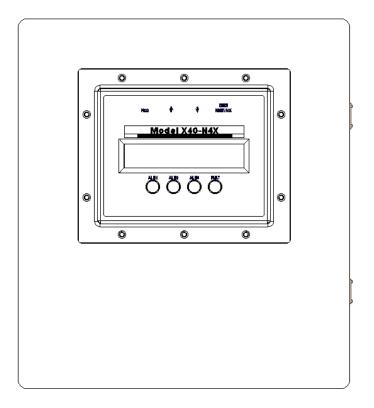
## **Instruction Manual**

# Model X40-08-N4X, Model X40-32-N4X Model X40-32-N1P, Model X40-32-N1P



# **Integrated Alarm and Control System**

This manual covers all Model X40 Control Systems

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X40 Instruction Manual i



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## 1. Introduction

#### 1.1 Features

The Teledyne Detcon X40 controller (Figure 1) is a multi-channel gas detection control system. The X40 serves as a host monitor/controller for a network of gas detection sensors and various other field devices. The controller offers a non-intrusive magnetic interface with backlit LCD display and Modbus<sup>TM</sup> technology that supports either wireless or a hard wire sensor connection. The X40 is equipped with an auto configure feature to automatically search the Modbus<sup>TM</sup> addresses for various Teledyne Detcon equipment associated with the controller and adds the equipment to the controller without user intervention.

Remote mounted gas detection sensors include any analog 4-20mA or RS-485 (Modbus™) serial devices such as;

- toxic gas,
- combustible gas, or
- oxygen deficiency sensors.

Remote field devices include contact closure inputs such as:

- liquid level,
- · temperature,
- pressure, or
- smoke detection devices.

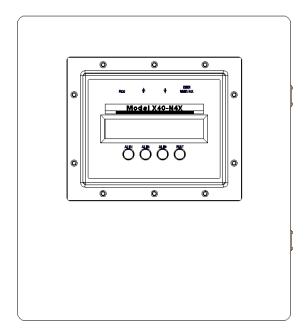


Figure 1 Model X40-N4X Controller

## 1.2 LCD Main Display Function

The main display is an  $1^{1}/_{4}$ " x 6" backlit LCD that is four lines by forty characters and displays up to eight configured channels at one time. The four internal magnetic switches are located above the backlit LCD display and offer basic navigation for a complete configuration of the controller (Section 5.1).

Real time sensor status includes:

- channel number
- gas concentration,
- device tag (gas type)
- alarm/fault status.

Each channel displays the current status of three alarm levels and a fault condition on the front panel LED indicators.



## 1.3 Modbus<sup>TM</sup> Communication

The controller uses the RS-485 Modbus<sup>™</sup> RTU protocol to communicate with RS-485 serial sensors and I/O modules. A secondary Modbus<sup>™</sup> port is addressable by a PLC, PC/HMI, DCS or other Modbus<sup>™</sup> RTU masterpolling devices.

#### Primary Modbus<sup>TM</sup> Interface (COMM1 Master)

Uses two-wire half duplex RS-485, 9600 baud, 8 data bits, 1 stop bit, no parity. Communicates directly with Modbus<sup>TM</sup> capable sensors and Teledyne Detcon's independently addressable I/O modules that operate on 11.5-30VDC.

#### Secondary Modbus<sup>TM</sup> Interface (COMM2 Slave)

The Modbus<sup>™</sup> slave interface communicates with the remote display or an additional controller.

## 1.4 Secure Digital Card (SD Card)

The X40 controller allows data logging when an SD memory card is installed. The card must be installed on the back of the PCA (printed circuit assembly) before the controller is powered up. The controller will automatically format the card (Section 4.0) and create the necessary files for data logging.

**NOTE:** Data logging does not occur during the first 10 minutes after power-up of the unit. This delay allows the sensors time to stabilize, so that inaccurate or faulty readings will not be logged during this stabilization period.

#### 1.5 I/O Modules and Connections

A maximum of 32 sensor channels are configurable for the X40 models and are customizable using Teledyne Detcon's I/O modules. Accommodation for the I/O modules relies on the type of enclosure utilized. Seamless system expansion is accomplished through DIN rail mounted and stackable modules. The modules communicate with the controller using Modbus<sup>TM</sup> technology and are available in four types;

- 4-20mA inputs
- dry contact inputs
- 4-20mA outputs
- relay outputs.

The analog sensors and analog field devices interfaced to the I/O modules communicate with the COMM1 Modbus<sup>TM</sup> master port on the X40 controller via the I/O Module. Serial sensors interface directly with the COMM1 port and do not require I/O modules. The types of sensors/field devices interfaced will dictate the I/O modules required for the X40 controller. Configuration inputs are completely field-configurable providing a distinctive combination of flexibility and expansion for the customer.

I/O modules are factory installed unless specifically instructed otherwise. The number of I/O modules that can be installed in the X40 enclosure is dictated by the enclosure due to physical space limitations. Additional I/O modules in excess of the maximum allowed for each enclosure must be mounted in a separate enclosure by the customer. The module limits for each enclosure varies dependent on the type of enclosure, and the set-up of the particular unit. The typical limitations are as follows:

- X40-32-N1P enclosure maximum of two I/O modules (Mounted on the back, outside)
- X40-08-N4X enclosure maximum of six I/O modules inside
- X40-32-N4X enclosure maximum of twelve I/O modules inside
- X40-32-N7 enclosure does not accommodate module installations

The X40 controller can be configured for various I/O module combinations at the Teledyne Detcon factory. Customer application/site specific information must be provided on the Configuration Form. Information provided is verified for correct quantity and type of I/O modules to support application/site requirements. The customer should supply the following site specific information:

- 1. Number of gas/sensor channels.
- 2. Teledyne Detcon sensor model number and I/O type (Modbus<sup>TM</sup> or 4-20mA) for each channel.



- 3. Range, units, and gas type for each channel.
- 4. Alarm level(s) for each gas channel.
- 5. Device Tag for each channel.
- 6. Assignment and set-up information for each relay contact.
- 7. Analog output requirements for each channel.

**NOTE:** The set-up configuration is executed by the user in the field (Section 5). Modifications are expected to take place on the site due to requirement changes and/or system expansions.

#### Teledyne Detcon I/O Modules (Purchased Separately)

Analog 4-20mA Sensor Inputs (DA-4)

- Provides power to any two or three wire field sensors
- Receives standard 4-20mA signal outputs from the sensors
- Four 4-20mA inputs to support up to four sensors
- Uses RS-485 Modbus<sup>TM</sup> RTU protocol to communicate with the controller and must have a unique Modbus<sup>TM</sup> address set between 01 and 7Fh.

#### Dry Contact Inputs (DI-4)

- Relay contact outputs from field devices can be connected
- Four relay contact inputs
- Can be installed on the DIN rail of the controller
- Uses RS-485 Modbus<sup>TM</sup> RTU protocol to communicate the state of the contact outputs from field devices and must have a unique Modbus<sup>TM</sup> address set between 01 and 7Fh.

## Analog 4-20mA Outputs (AO-4)

- Provide a 4-20mA output equal to the current concentration reading reported to the controller for the associated channel.
- Uses RS-485 Modbus<sup>™</sup> RTU protocol to receive the 4-20mA output levels. AO-4 modules must have a unique Modbus<sup>™</sup> address set between A0 and AFh.

## Alarm Relay Outputs (RL-4)

- Alarms can be used to control (fire) annunciating devices or signal inputs to other control devices.
- Four Form C, Single Pole Double Throw (SPDT), 5 Amp relay contacts each assigned specifically to one alarm.
- Uses RS-485 Modbus<sup>™</sup> RTU protocol to communicate the outputs and must have a unique Modbus<sup>™</sup> address set between 80 and 8Fh.
- The X40 controller is configured with a maximum of eight separate relay banks each holding up to two RL-4 modules.
- Anytime a specific alarm (e.g. Alarm 3) is fired for a particular module in a bank (e.g. Bank2), all corresponding alarms (e.g. Alarm 3's) for all modules in that particular bank (e.g. Bank2) are also triggered.

#### RS-485 Serial Gas Sensors (Modbus<sup>TM</sup>)

RS-485 Serial gas sensors can be interfaced directly with the X40 controller without the use of I/O modules by connecting the sensors in a series to the primary RS-485 Modbus<sup>TM</sup> interface (RS-485 Master Port).

## 1.6 Enclosure Types

The X40 controller is available in three enclosure types to accommodate various customer needs and configurations. The number of I/O modules varies depending on the enclosure type and configuration.

#### N1P Enclosure

The Model X40-32-N1P controller is housed in a NEMA 1 panel mount enclosure for indoor use. The internal power supply of the N1P controller converts 100-120/220-240VAC to 24VDC and can power a maximum of 32 sensors and associated I/O modules. A maximum of two I/O modules can be installed on the outside of the controller. Additional modules must be mounted separately by the customer.

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The power supply for the N1P is capable of handling AC inputs from 100-120/220-240VAC, 50-60Hz without degradation. The X40 controller can be powered by an external DC source that meets the input requirements (11.5-30VDC) of the unit if AC power is not preferred or available. DC power can be used for primary or back-up power in the event of an AC power failure. RS-485 and power out are provided for connection to sensors attached to the unit.

#### N4X Enclosure

The X40 controller is available in two different size models for the N4X enclosure type. Both the X40-08-N4X and X40-32-N4X controllers are housed in a NEMA 4X water/corrosion proof enclosure for indoor/outdoor use. The power supplies for both enclosure types are capable of handling AC inputs from 100-120/220-240VAC, 50-60Hz without degradation. The X40-N4X can be powered by an external DC source that meets the input requirements (11.5-30VDC) of the X40 if AC power is not preferred or available. This input can be used for primary power or back-up power in the event of an AC power failure. The DC output voltage is capable of delivering a maximum of 2 Amps of current to the sensors attached to the X40 controller.

RS-485 master port and power out are provided for connection to serial sensors attached to the unit.

The X40-08-N4X enclosure houses a maximum of six I/O modules inside of the controller and is capable of communicating with a maximum of 32 devices. The enclosure can incorporate integral alarms such as an 8" strobe mounted on the top of the enclosure, horn, or both.

The X40-32-N4X enclosure houses a maximum of twelve I/O modules inside of the controller and communicates with up to 32 devices.

#### N7 Enclosure

The X40-32-N7 controller is housed in an explosion proof NEMA 7 enclosure for indoor/outdoor use. The N7 enclosure does not accommodate module installations. Modules must be mounted externally by the customer. Any sensors and associated I/O modules will need to be powered separately by the customer.

The X40 controller can be powered directly by an external DC source provided by the customer, which meets the input requirements (11.5-30VDC) of the unit. A plug-in male connector is provided for input wiring terminations. A plug-in male connector provides quick disconnect convenience during replacement or servicing.

An optional AC/DC converter board inside a condulet/J-Box is available from Teledyne Detcon to only power the N7 controller with an AC voltage source. The converter uses AC inputs between 100-240VAC and provides a 24VDC (up to 167mA) output. Power to I/O modules or sensors must be provided by the customer.

Teledyne Detcon offers an optional mounting plate for mounting the X40-32-N7 controller to a pole.

#### 1.7 Alarms and Fault Condition

The alarms (Alarm 1, Alarm 2, Alarm 3, and Fault) can be used to control annunciating devices or as signal inputs to other control devices. The field configurable magnetic user interface permits alarm values and fault condition to cause an assigned relay or bank of relay outputs to fire, triggering external alarm devices. The assigned relay outputs will return to normal state when a gas alarm or a fault condition clears. Additionally, an external manual switch can be wired to the X40, acting as an acknowledge/reset switch (Section 1.12).

When the X40 is in alarm, the display will remain on the channel group with the alarm. When there is more than one alarm/fault, the controller will cycle through group pages with alarms/faults including the transceiver, RL-4/alarm station, and AO-4 group pages. The user can manually cycle to any group page that exists using the arrow switches. After a time out period, the X40 will resume page cycle protocols based upon the existence of alarms/faults. Four LED indicators on the front panel show alarm/fault alarm output status and are labeled respectively as ALM 1 (yellow), ALM 2 (yellow), ALM 3 (red), and FAULT (blue).

All alarms can be configured Energized/De-Energized, Latching/Non-Latching and Silenceable/Non-Silenceable for the relays.

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#### **Energized Mode**

The normally open contact is closed if the alarm level has not been reached or if the sensor is not in fault. Energized mode provides for fail-safe operation since a loss of power or cable failure will cause the contact to be open.

#### **De-Energized Mode**

The normally open contact is open if the alarm level has not been reached or if the sensor is not in fault.

#### Silenceable

The corresponding alarm LED and relay can be deactivated by acknowledging the Alarm Silence function on the front panel of the X40 controller or by activating the external acknowledge switch if installed (Section 7.0).

#### Non-Silenceable

The corresponding alarm LED and relay will remain activated until the cause of the alarm or fault is clear.

#### **Latching Mode**

The relay can be deactivated after the alarm condition has cleared by acknowledging the Alarm Reset function on the front panel of the X40 controller or by activating the external reset switch if installed (Section 7.0).

#### **Non-Latching Mode**

The relay is deactivated as soon as the sensor alarm or fault condition is clear.

## 1.8 System Operation

The setup of the controller is critical for proper operation. Modbus<sup>TM</sup> addresses must be correct on all the devices connected to the controller before the controller will acknowledge the devices. Each wireless sensor must have a unique Modbus address (refer to sensor manual for details). The number of sensors is determined during auto configure if the addresses on the sensors and modules are set correctly.

The operator interface of the X40 utilizes four internal magnetic switches located above the controller's backlit LCD display. The four switches provide a non-intrusive interface and allow for complete configuration of the controller and are labeled as follows:

- PROG,
- † (Up Arrow),
- ↓ (Down Arrow) and
- ENTER.

The ENTER switch also doubles as a RESET/ACK switch from the Main Display only (not in Menu Mode).

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## 1.9 Operator Interface

Reference the Menu Flow Chart (Figure 2) to learn how to easily navigate the menus and make changes.

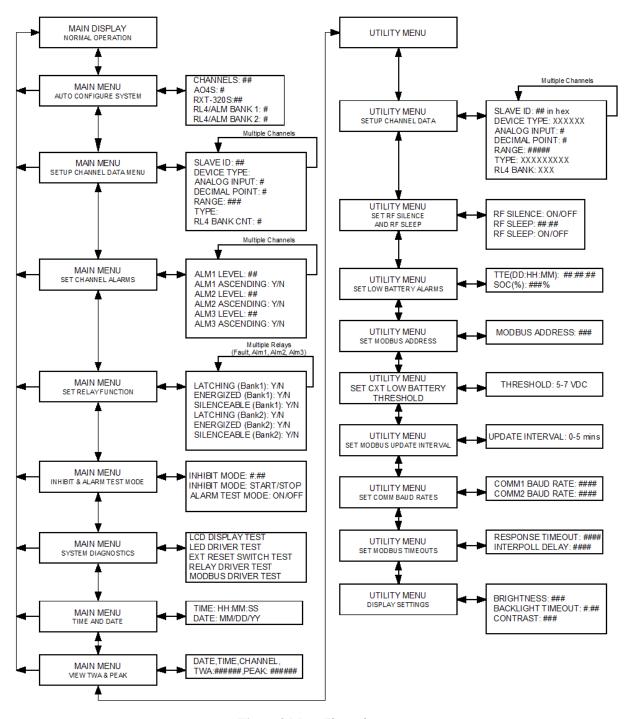


Figure 2 Menu Flow Chart

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#### **Magnetic Programming Tool**

The magnetic programming tool (Figure 3) is used to operate the magnetic switches. For switch activation, the programming magnet is briefly held on the switch marker ( $\otimes$ ) and then removed. This action will be referred to as a "swipe" for the remainder of this manual.



Figure 3 Magnetic Programming Tool

#### **Front Panel User Interface**

The front panel user interface (Figure 4) contains four switches necessary to configure the X40 controller.

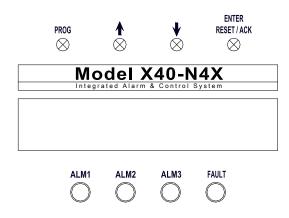


Figure 4 Front Panel User Interface

#### **PROG Switch**

From the Main Display, the PROG switch enters into the Main Menu. Once inside the Main Menu, the PROG switch acts as an "Escape" switch that moves backwards in the menu flow chart.

**NOTE:** While in Main Menu mode there are no updates to gas readings and hence no alarms will take place.

#### ↑ Up Arrow Switch

This switch moves the user up the Main Menu flow chart. It is also used to change selected entries in the menu selections in the upward direction.

#### **↓** Down Arrow Switch

This switch moves the user down the Main Menu flow chart. It is also used to change selected entries in the menu selections in the downward direction.

#### **ENTER and RESET/ACK Switch**

This switch has multi-purpose use:

- The ENTER function is used to accept selections in all menu screens and to execute the Reset and Acknowledge functions.
- The Reset function releases all latched relays once the alarm/fault condition has cleared.
- The Acknowledge function will disengage any silenceable relays that are in an active state. This is used to silence alarms once the end-user has assessed the alarm condition.
- The RESET/ACKNOWLEDGE function of the switch is only applicable from the Main Display and not while in Main Menu mode.

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## 1.10 Main Display Functions

When the X40 is in alarm, the LCD display will stay on the channel group with the channel in alarm. If more than one alarm/fault exists, the X40 will cycle through group pages with alarms/faults including the transceiver, RL-4/alarm station, and AO-4 group pages. At any time the user can manually cycle to any group page using the arrow switches. After a time out period (15 seconds), the X40 will resume page cycle protocols based upon the existence of alarms/faults. Four LED indicators on the front panel show alarm and fault alarm output status. The LEDs represent ALM 1 (yellow), ALM 2 (yellow), ALM 3 (red) and FAULT (blue).

**NOTE:** The X40 only cycles through sensor group pages when no alarms/fault exist

#### **Sensor Group**

## XX> YYY "Device Tag"

**XX** – represents the corresponding channel number

YYY – the gas concentration value

"Device Tag" – Either user enter tag or:

- IN ALARM# = If any channel is in any gas alarm condition, # is the alarm level.
- IN FAULT = If any gas channel is in fault.
- COMM ERR = If any channel is not appropriately communicating with the device.

#### **Transceiver Group**

#### WTXX 'Status' YYY%

**XX** – represents the transceiver Modbus<sup>TM</sup> slave address.

'Status' – Status message of the alarm station.

- OFFLINE = Not communicating.
- DC POWER = Communicating; line powered.
- BATT ERR = Communicating; cannot read smart battery pack.
- LOW BATT = Communicating; battery life is below the set threshold.
- 45+ DAYS = Communicating; smart battery pack has more than 45 days before empty.
- 0-45 DAYS = Communicating; the number of days until smart battery pack is empty.
- x.xxV = Communicating; the voltage of the installed non-rechargeable battery

YYY% - represents the link quality of the transceiver.

#### **RL4/Alarm Station Group**

#### Hardwired RL4 Module

#### RMXX> 'Status'

**XX** – represents the RL4 Modbus slave address.

**'Status'** – Status message of the RL4 module.

- COMM ERR = Not communicating with module.
- RL4 MODULE = Communicating with module.

#### **Wireless Alarm Stations**

ASXX 'Status' YYY%

**XX** – represents the alarm station Modbus slave address.

'Status' – Status message of the alarm station.

- OFFLINE = Not communicating.
- DC POWER = Communicating; line powered.
- BATT ERR = Communicating; cannot read smart battery pack.
- LOW BATT = Communicating; smart battery state of charge below the set threshold.
- 0-100% = Communicating; current state of charge of the smart battery pack.



YYY% - represents the link quality of the alarm station.

#### **AO-4 Group**

AMXX> 'Status'

**XX** – represents the AO-4 module Modbus slave address

'Status' – Status message of the AO - 4 module

- COMM ERR = Not communicating with module
- AO-4 MODULE = Communicating with module

#### 1.11 Menu Function

The X40 controller setup is accomplished through the Main Menu and consists of seven menu items:

- 1. Auto Configure System
- 2. Setup Channel Data
- 3. Set Channel Alarms
- 4. Set Relay Function
- 5. Inhibit & Alarm Test Mode
- 6. System Diagnostics
- 7. Time and Date
- 8. View TWA & Peak

#### **Auto Configure System**

The Auto Configure System automatically configures the X40 controller when other Teledyne Detcon devices are installed as part of the control system. When activated, the controller searches for Teledyne Detcon serial sensors, RL-4 modules/alarm stations, AO-4 modules and wireless radio modules.

#### **Setup Channel Data**

Setup Channel Data displays the Modbus ID, device type, range, and gas type for each channel. The assigned RL4 bank and number of analog inputs (for channels using an RXT-320) is also displayed. Only the gas type can be changed by the user. No other values on this screen can be changed.

#### **Set Channel Alarms**

All sensors have three alarm settings ALM1 (Alarm 1), ALM2 (Alarm 2) and ALM3 (Alarm 3). The user establishes the alarm levels for each sensor depending on the range. The values represent the alarm level set points and entered in 5% increments of the full-scale range selected for that channel. In ascending mode the relay is activated when the concentration is *above* the alarm threshold. In descending mode, the alarm relay is activated when the concentration is *below* the alarm threshold. Alarms are usually ascending, with the exception of oxygen sensors. The alarm ascending level can be either Y (Yes) or N (No).

#### Set Relay (Alarm) Functions

The Set Relay Functions menu enables configuration (Latching, Energized and Silenceable) of the relays in Bank1-8. Each relay bank has three relay outputs for ALM1, ALM2 and ALM3 and a fourth relay output for the Fault condition. All relays in the bank must be configured for the following three settings:

- Latching or Non-Latching
- Energized or De-Energized,
- Silenceable or Non-Silenceable

#### **Inhibit and Alarm Test Mode**

The Inhibit and Alarm Test Mode permits the user to inhibit functionality of alarms in the network, simulate alarm conditions and verify relay contacts. The Inhibit mode disables alarm outputs while sensor are being calibrated or tested. The Alarm Test Mode simulates alarm conditions by increasing the gas readings from zero for all active gas channels at increments of 5% full scale then decrease back to zero and exit the test mode.

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#### **System Diagnostics**

The System Diagnostics menu performs complete functionality tests for:

- LCD display
- Panel LED's
- External reset switch
- Relays
- Modbus<sup>TM</sup> interface

#### **Time and Date**

The Time and Date menu enables the user to effortlessly establish the time and date. The time will be displayed as military time (24hrs) in hours, minutes and seconds. The date will be displayed as the month, day and two digit year. If the time and/or date are not correct, they can be updated.

#### View TWA and Peak

The View TWA and Peak menu permits viewing the recorded time weighted average (TWA) and peak readings for each channel represented by its assigned gas sensor. The data is recorded on the SD card with the date, time, channel number, TWA and peak readings each time the controller polls a sensor. Data on the SD card is viewed by using the Teledyne Detcon Log File Viewer application on a computer.

## 1.12 Optional Remote Alarm Reset/Acknowledge Switch

An optional remote Alarm Reset/Acknowledge switch enables the user to reset or acknowledge alarms without having to open the X40 enclosure. The switch is a normally open push button mounted on the bottom or side of the NEMA 4X enclosure. For the N1P and N7 enclosures, the switch must be mounted externally (e.g. bottom of the J-Box).

## 1.13 Wireless Option

The Model X40 controller offers a wireless option that uses Modbus<sup>TM</sup> technology to connect the controller and other devices to a wireless platform. The local Modbus<sup>TM</sup> communication uses a wireless grid of transceivers to broadcast information throughout the wireless network, creating a seamless network of Modbus<sup>TM</sup> devices that are not physically connected. The transceiver operates at 2.4GHz and conforms to non-licensed radio frequency usage worldwide. Spread spectrum technology supports integrity and security for the wireless network.

Wireless applications can be a single field device communicating with a host controller or multiple field devices forming a network of subscribers. Each device in the network is assigned a Network ID and a Modbus™ address. If radio communication is impossible due to distance or obstruction, each slave device is capable of locating an alternate route using an additional radio to communicate with the designated device. This innovative technology is designed to create a robust network that automatically routes around congestion and line-of-sight obstacles while improving throughput as subscriber device density increases. Refer to the Wireless Radio Module instruction manual for detailed information.

#### Wireless Radio Module Mounting

Teledyne Detcon's wireless radio modules are factory installed. The radio module has a rotary dial for setting the RF channel. The radio module, wireless sensors, and wireless alarm stations must all be set to the same RF channel to operate correctly.

**NOTE:** The radio module, wireless sensors, and wireless alarm stations must all be set to the same RF channel to operate correctly.

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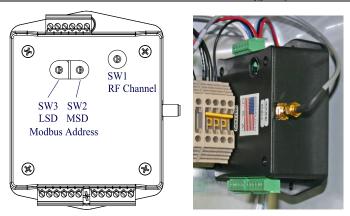


Figure 5 Radio Module

For NEMA 1 or NEMA 12 units the antenna is typically mounted separately, using Teledyne Detcon's remote antenna mounting kit. On NEMA 4 units the antenna can be installed on the top of the enclosure or separated up to 50m using Teledyne Detcon's remote antenna mounting kit (Section 2.3). On N7 units the antenna is mounted on the Transceiver, and is part of the unit (Section 2.4). Teledyne Detcon's antennas are vertically polarized. This means that there is an RF 'Dead-Zone' directly above and below any transmitting antenna. Because of this, any device with an antenna that is located near an elevated antenna should be placed at least as far from the elevated antenna as the antenna is high. For example, if an antenna is 20ft. off the ground, the nearest antenna should be at least 20 ft. away.

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## 2. Installation

## 2.1 Safety Guidelines

If equipment is used in a manner not specified by Teledyne Detcon, the protection provided by the equipment may be impaired.



**CAUTION:** The user must consult this manual for more information about any location marked with this symbol.

*ATTENTION:* L'utilisateur doit consulter ce manuel pour plus d'informations sur tout emplacement marqué de ce symbole



**DANGER:** Danger of electrical shock. User must ensure that power has been disconnected prior to installation or servicing of the equipment.

**DANGER:** Danger d'électrocution. L'utilisateur doit s'assurer que l'alimentation a été débranchée avant l'installation ou l'entretien de l'équipement.



PROTECTIVE EARTH TERMINAL This symbol identifies a terminal that is the connection point for a protective earth conductor. Only the protective earth conductor should be connected here.



FUNCTIONAL EARTH TERMINAL

This symbol identifies a terminal that provides an earth ground reference point. These terminals are not for safety earthing purposes.

#### 2.2 N1P and N1R Enclosure Installation



*CAUTION:* The X40-32-N1P and X40-32-N1R units can power a maximum of 32 sensors. Damage to the power supply may result if the maximum number of sensors is exceeded.

*ATTENTION:* Les boîtiers X40-32-N1P et X40-32-N1R peuvent alimenter un maximum de 32 capteurs. L'alimentation électrique peut être endommagée si le nombre maximal de capteurs est dépassé.

- 1. Provide a panel opening that is 9.25" wide by 7.5" high for the N1P controller. The N1R controller is meant to be mounted in a 19" Rack.
- 2. Securely mount the X40-32-N1P or X40-32-N1R controller at an indoor location using the mounting dimensions provided in Figure 6 and Figure 7. The N1R is made to fit a 19" Rack.

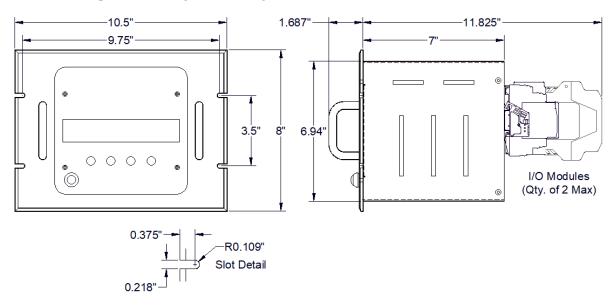


Figure 6 N1P Controller Mounting and Dimensional View



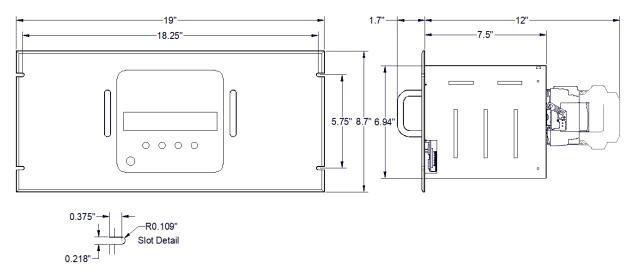


Figure 7 N1R Controller Mounting and Dimensional View

**NOTE:** If the AC and DC wiring are run in the conduit, ensure that the AC wiring is not housed in the same conduit as the DC signal/wiring.

**NOTE:** The power supply for the X40-32-N1P and X40-32-N1R is capable of handling AC inputs between 100-120/220-240VAC, 50-60Hz without degradation.

- 3. Install AC or DC power as follows: (Refer to Figure 8.)
  - a. Install AC power by connecting the 100-120/220-240VAC input wiring to the terminals labeled VAC (L1), NEU (L2), and GROUND.
  - b. Install DC power by connecting the 11.5-30VDC to the terminals of the DIN rail mounted terminal block labeled **24VDC** and **DC Comm**.

**CAUTION:** Equipment and equipment to be electrically connected shall use safety approved wire/cable in conjunction with appropriate and compatible protective cable gland, all of which meet the requirements of the max equipment rating (250VAC, 5A) and any local electrical codes, regulations and standards. The cable used to connect to the terminals of the X40-32-N1P and X40-32-N1R must be rated for a minimum of 105°C.



*ATTENTION:* L'équipement et l'équipement à connecter électriquement doivent utiliser un fil/câble approuvé pour la sécurité en conjonction avec un presse-étoupe de protection approprié et compatible, qui répondent tous aux exigences de la puissance nominale maximale de l'équipement (250 VAC, 5 A) et à tous les codes, réglementations et réglementations électriques locaux. normes. Le câble utilisé pour se connecter aux bornes des X40-32-N1P et X40-32-N1R doit être conçu pour un minimum de 105 °C.

**NOTE:** The DC input voltage should be capable of delivering at least 4.2 Amps of current to the load (100 Watts @ 24VDC).

**NOTE:** The supply of power should be from an isolated source with over-current protection and an input voltage range between 11.5-30VDC.

4. Connect the external Modbus<sup>TM</sup> sensors at the RS-485 connections labeled **RS-485 Master: 'A', 'B',** and 'Shld' (Figure 8).

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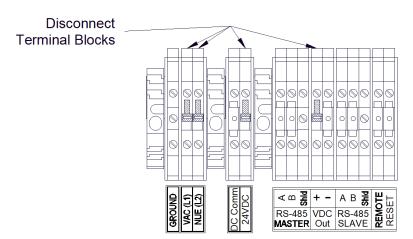


Figure 8 N1P and N1R Connections

- 5. If 24VDC is required to power external sensors, connect the sensors to the power terminals labeled **VDC** Out, '+' and '-'.
- 6. If linking the X40 enclosure to an RD-64X remote display unit, connect the unit to the terminals labeled **RS-485 Slave:** 'A', 'B', and 'Shld'.

#### 2.3 N4X Enclosure Installation

**CAUTION:** The power supply for the X40-08-N4X controller can power a maximum of eight sensors even though the controller is capable of communicating with 32 devices. An additional power supply will be required if powering more than eight sensors or an upgrade to Model X40-32-N4X is needed which can power a maximum of 32 sensors. Damage to the power supply may result if the maximum number of sensors is exceeded.



**ATTENTION:** L'alimentation du contrôleur X40-08-N4X peut alimenter un maximum de huit capteurs, même si le contrôleur est capable de communiquer avec 32 appareils. Une alimentation supplémentaire sera nécessaire si vous alimentez plus de huit capteurs ou si une mise à niveau vers le modèle X40-32-N4X est nécessaire, qui peut alimenter un maximum de 32 capteurs. L'alimentation électrique peut être endommagée si le nombre maximal de capteurs est dépassé.



**CAUTION:** The wall attachments must be able to withstand a force four times the weight of the equipment.

**ATTENTION:** Les fixations murales doivent pouvoir supporter une force quatre fois supérieure au poids de l'équipement



**CAUTION:** The X40 must be mounted in a location that does not impair the operation of the external disconnection device. Internal Disconnect Terminal Blocks are provided for the removal of power at the unit when needed.

*ATTENTION*: Le X40 doit être monté dans un endroit qui ne gêne pas le fonctionnement du dispositif de déconnexion externe. Des borniers de déconnexion internes sont fournis pour couper l'alimentation de l'unité en cas de besoin.

1. Securely mount the enclosure in accordance with the dimensions provided in Figure 9 (X40-08-N4X) or Figure 10 (X40-32-N4X).

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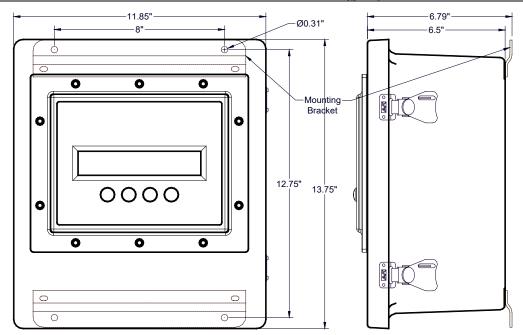


Figure 9 X40-08-N4X Controller Mounting and Dimensional View

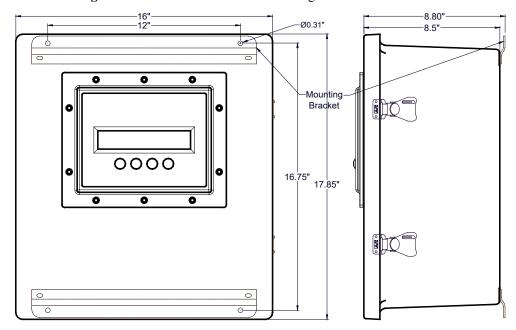


Figure 10 X40-32-N4X Controller Mounting and Dimensional View

**NOTE:** If the AC and DC wiring are run in conduit, ensure that the AC wiring is not housed in the same conduit as the DC signal/wiring.

**NOTE:** The internal power supply in the X40-08-N4X and X40-32-N4X converts 100-120/220-240VAC to 24VDC. Up to 2A @ 24VDC is available to power sensors attached to the X40. If more than 2A @ 24VDC is required, then the user must supply an additional power supply.

**NOTE:** The power supply for the X40-08-N4X and the X40-32-N4X are capable of handling AC inputs from 100-120/220-240VAC, 50-60Hz without degradation.

**NOTE:** Electrical connections after installing the device to be made by only a qualified electrician to national and local electric codes.

- 2. Install AC power as follows (Figure 14):
  - a. Install AC power by connecting the 100-120/220-240VAC input wiring to the terminals labeled VAC (L1), and NEU (L2).

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**NOTE:** The cable penetration for the AC power must be made in the bottom of the enclosure (See Figure 13). All penetrations must use a NEMA4 rated cable gland (Appleton p/n CG-2575 or equivalent) to prevent water ingress and restrict access to the internal circuits of the X40.

- b. Locate the ground terminal on the back plate of the N4X enclosure (Figure 11).
- c. Remove both nuts and the internal ground conductor
- d. Connect the protective earth conductor to the ground terminal with one lock washer, the protective earth conductor, a second lock washer on top of the conductor, a nut on top of the conductor, the circuit ground connector, and then a nut.

**NOTE:** Ensure that the protective earth conductor is connected directly to the ground terminal.

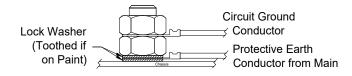


Figure 11 N4X Protective Earth Connector

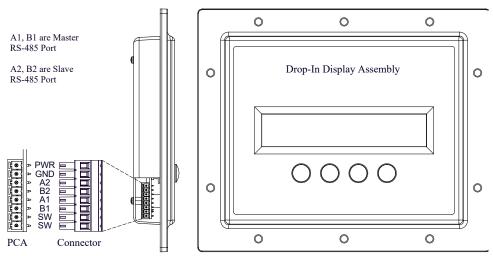


Figure 12 Display Wiring

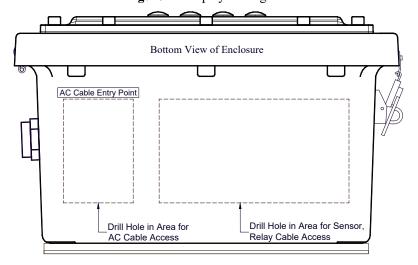


Figure 13 Cable Entry Points

- 3. Tie the AC power conductors together with a tie-wrap.
- 4. To maintain the safety approval for the X40, the user must install a circuit breaker(s) near the X40 so that it can be easily reached and labeled as the power disconnection device for the X40. The installed AC circuit breakers should be rated for 3A.

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**NOTE:** The equipment switch or circuit-breaker employed as a disconnecting device shall meet the relevant requirements of IEC 60947-1 and IEC 60947-3 and be suitable for the application. Internal Disconnect Terminal Blocks are provided for the removal of power at the unit when needed.

**CAUTION:** Equipment and equipment to be electrically connected shall use safety approved wire/cable in conjunction with appropriate and compatible protective cable gland, all of which meet the requirements of the max equipment rating (250VAC, 5A) and any local electrical codes, regulations and standards. The cable used to connect to the terminals of the X40-32-N4X must be rated for a minimum of 105°C



*ATTENTION:* L'équipement et l'équipement à connecter électriquement doivent utiliser un fil/câble approuvé pour la sécurité en conjonction avec un presse-étoupe de protection approprié et compatible, qui répondent tous aux exigences de la puissance nominale maximale de l'équipement (250 VCA, 5 A) et à tous les codes, réglementations et réglementations électriques locaux. normes. Le câble utilisé pour se connecter aux bornes du X40-32-N4X doit être évalué pour un minimum de 105 °C

- 5. Install the DC power as follows:
  - a. Install external DC power by connecting the 11.5-30VDC to the terminals of the TB1 DIN rail mounted terminal block labeled **24VDC** and **DC Comm** (Figure 14). The equipment supply wiring must be safety approved and rated for at least 7.5A.

**NOTE:** The equipment switch or circuit-breaker employed as a disconnecting device shall meet the relevant requirements of IEC 60947-1 and IEC 60947-3 and be suitable for the application. Internal Disconnect Terminal Blocks are provided for the removal of power at the unit when needed.

- b. To maintain the safety approval for the X40, the user must install an external disconnect switch or circuit breaker near the X40 so that it can be easily reached and labeled as the disconnection device for the X40. The installed DC circuit breaker should be rated for 5A.
- c. The unit does come equipped with Disconnect Terminal Blocks on the input power lines. These can be used to connect or disconnect power at the unit.

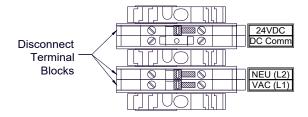


Figure 14 N4X AC/DC Inputs

6. Connect the external Modbus<sup>TM</sup> sensors at the RS-485 connections labeled **RS-485 Master** and 'A', 'B', and 'Shld' (Figure 15).

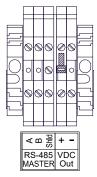


Figure 15 N4X RS-485 Master Port Connections

7. If 24VDC is required to power external sensors, connect the sensors to the power out labeled **VDC Out:** '+' and '-'.

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8. If linking the X40 enclosure to an RD-64X remote display unit, connect the unit to the slave port terminals labeled **RS-485 Slave:** 'A', 'B', and 'Shld' (Figure 16).

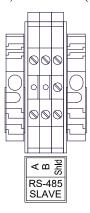


Figure 16 N4X RS-485 Slave Port Connections

9. If the X40-N4X was ordered with the wireless option, the radio module is installed in the enclosure and an antenna connector is provided on the top of the enclosure (Figure 17). Mount the external antenna in an appropriate location with an unobstructed line-of-sight to the wireless devices. Connect the RF cable from the connector on top of the X40 to the antenna.

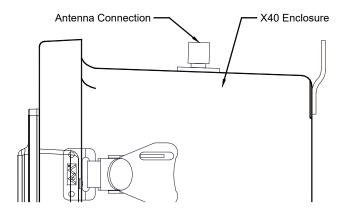


Figure 17 N4X Antenna Connector

**CAUTION:** Any slave device near an elevated or remote mounted antenna needs to be at least as far from the antenna as the antenna is high. For example, if the antenna is 20ft. high, then the nearest slave device should be at least 20 ft. away.



*ATTENTION:* Tout appareil esclave à proximité d'une antenne surélevée ou montée à distance doit être au moins aussi éloigné de l'antenne que l'antenne est haute. Par exemple, si l'antenne mesure 20 pieds. haut, alors l'appareil esclave le plus proche doit être à au moins 20 pieds.

#### 2.4 N7 Enclosure Installation

**CAUTION:** The X40-32-N7 controller can support up to a maximum of 32 sensors and any associated I/O modules, but no I/O modules can be installed in the controller. All I/O modules must be mounted separately by the customer. The N7 version does not supply power to sensors. Power must be supplied by the customer for sensors and any I/O modules. Damage to the controller may result if the maximum number of sensors is exceeded.



*ATTENTION:* Le contrôleur X40-32-N7 peut prendre en charge jusqu'à un maximum de 32 capteurs et tous les modules d'E/S associés, mais aucun module d'E/S ne peut être installé dans le contrôleur. Tous les modules E/S doivent être montés séparément par le client. La version N7 n'alimente pas les capteurs. L'alimentation doit être fournie par le client pour les capteurs et tous les modules d'E/S. Des dommages au contrôleur peuvent survenir si le nombre maximal de capteurs est dépassé

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1. Securely mount the X40-32-N7 controller in accordance with the mounting dimensions provided in Figure 18.

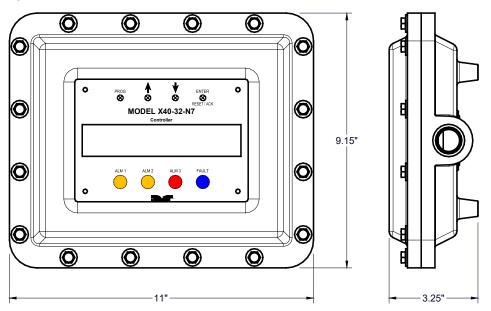


Figure 18 N7 Controller Mounting and Dimensional View

- 2. Verify that appropriate cable glands are used to maintain the enclosure rating.
- 3. If the N7 enclosure is not provided with a J-Box from the factory, remove the faceplate from the controller enclosure to access the PCA (Figure 19). All appropriate wiring must be connected directly to the PCA J7 in this configuration.

·	J7 Connections are as follows:				
_	PWR/GND	DC power connection to power X40-32-N7 controller			
NOTE	A2/B2 Secondary Modbus <sup>TM</sup> connection (COMM2 Slave)				
	A1/B1	Primary Modbus <sup>TM</sup> connection (COMM1 Master)			
	SW	External switch connection for RESET/ACK function (Normally Open)			

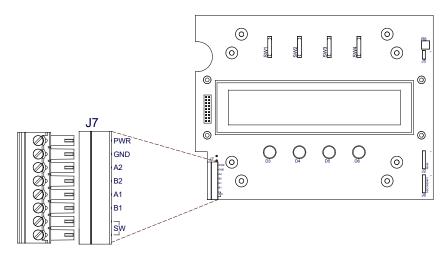


Figure 19 N7 Controller PCA

*CAUTION*: The cable used to connect to the terminals of the X40-32-N7 must be rated for a minimum of 105°C.



*ATTENTION:* Le câble utilisé pour se connecter aux bornes du X40-32-N7 doit être conçu pour un minimum de 105 °C

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4. If the unit comes with the optional mounting plate and a Condulet, attach the mounting plate assembly to a pole with two U-Bolts secured through the  $^{7}/_{16}$ " rectangle holes of the mounting plate base (Figure 20).

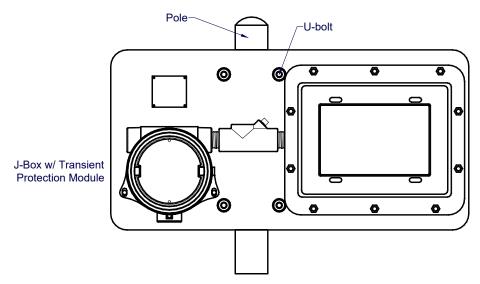


Figure 20 N7 Controller Assembly w/Mounting Plate

**NOTE:** It is highly recommended to install the cable inside rigid metal conduit to eliminate potential EMI and RFI interference and to maintain a Class I Division I rating.

**NOTE:** A 6-32 or 8-32 threaded exterior ground point is provided on most junction boxes for an external ground. If the transceiver assembly is not mechanically grounded, an external ground strap *must* be used to ensure that the transceiver is electrically grounded.

**NOTE:** Proper electrical installation of the wireless radio module assembly is critical for conformance to Electrical Codes and to avoid damage due to water leakage. A conduit seal is typically required to be located within 18" of the transceiver assembly if a conduit run is required. Crouse Hinds type EYS2, EYD2 or equivalent are suitable for this purpose.

**NOTE:** Any unused ports should be blocked with suitable  $^{3}/_{4}$ " male NPT plugs. Teledyne Detcon supplies one  $^{3}/_{4}$ " NPT male plug with each J-box enclosure. If connections are other than  $^{3}/_{4}$ " NPT, use an appropriate male plug of like construction material.

**NOTE:** Use suitable cord connectors (cable glands) for cable entry to the X40 controller or the connecting Junction Box..

**NOTE:** The Teledyne Detcon Warranty does not cover water damage resulting from water leaking into the enclosure.

5. If the unit comes with an AC/DC Adapter, ensure that the AC signal/wiring is not housed in the same conduit as the DC signal/wiring.

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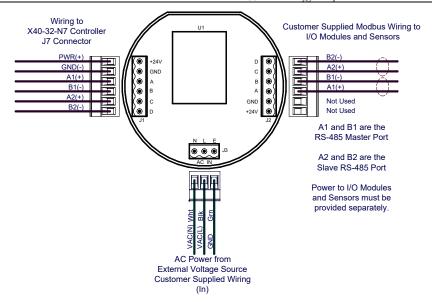


Figure 21 N7 AC/DC Converter Board Wiring

follows:

*CAUTION*: The cable used to connect to the terminals of the X40-32-N7 must be rated for a minimum of 105°C.

*ATTENTION:* Le câble utilisé pour se connecter aux bornes du X40-32-N7 doit être conçu pour un minimum de 105 °C

- 6. Install AC power and I/O connections when the N7 is supplied with a J-Box and an AC/DC converter as follows:
  - a. Connect 100-240VAC input wiring to the **J3** connector (labeled **AC IN)** of the converter board.
  - b. J1 should come wired and connected to the controller from the factory. Ensure that J1 is properly connected to the AC/DC Converter.
  - c. Interface the I/O modules and sensors to the X40 controller through the **J2** connector of the AC/DC converter board (Figure 21).

NOTE: The terminals on the J3 connector are labeled N (neutral), L (line power) and E (earth ground).

NOTE: An optional Transient Protection board is available from Teledyne Detcon for use with external DC

- Supply. When using external DC power to power the controller the input power must be 11.5-30VDC.

  7. For units that will be wired to an external power source connect the external power and Modbus<sup>TM</sup> as
  - a. Connect the 11.5-30VDC to the terminals Labeled "+" and "-" on the transient Protection PCA.
  - b. Connect the RS-485 Master Port to the terminals labeled "A" and "B" on the Transient Protection PCA.

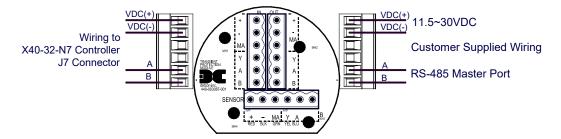


Figure 22 N7 DC Power Wiring

8. After applying power to the unit observe that the controller display starts and the unit will go through the boot-up sequence (Section 3.12).

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#### **NEMA 7 units with RXT-320 Transceiver**

NEMA 7 units can come pre-configured with a RTX-320 Transceiver. These units will come pre-assembled on a mounting plate that can be mounted on a  $2\sim3$ " pole.

## **Battery Operated Units**

Battery operated units come prewired and set up for installation:

- 1. Attach the mounting plate assembly to a pole with two U-Bolts secured through the 7/16" rectangle holes of the mounting plate base (Figure 23).
- 2. The wireless radio module connected to the Modbus<sup>TM</sup> master port is to be used with a Teledyne Detcon Smart Wireless battery pack. These units come with the Model 100 Terminal Board will be mounted in the condulet/J-Box (Figure 24). Refer to Table 1 for descriptions of the connector plugs.

Come as battery operated, DC or AC operated.

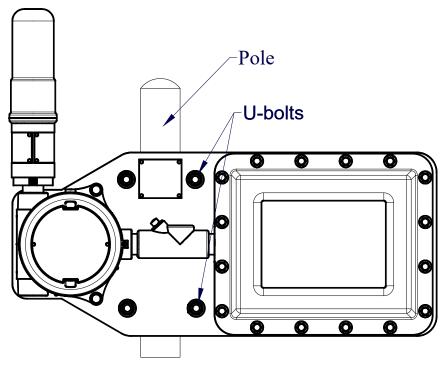


Figure 23 Typical NEMA7 with Transceiver

Table 1 X40 Model 100 Terminal Board Connector Plugs

J1	4-Pin Connector	Modbus™ Out (Wireless Transceiver Option)	
J2	6-Pin Header	Wireless Transceiver Programming Header	
J3	6-Beau Connector	Battery operation or display interface dependent on sensor configuration	
J4	4-Pin Connector	Modbus™ In – Connects to X40	
J5	Not used		
J6	Not used		
J7	4-Pin Connector	Connection to solar panel	
J8	6-Pin Connector	Wireless Transceiver	
J9	5-Pin Header	Terminal Board Programming	

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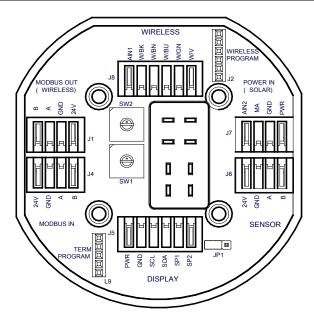


Figure 24 Model 100 Terminal Board

3. Ensure that the two rotary switches on the Model 100 Terminal Board are set to the Modbus<sup>TM</sup> address (F0h) for the wireless radio module of the X40 controller. The Model 100 Terminal Board should come set from the Teledyne Detcon factory and should be set to the address to F0h. Access the terminal board and locate the switches shown in Figure 25. The MSD (most significant digit) "F" is represented by the top rotary switch (closest to the J1 connector) and the LSD (least significant digit) "0" is represented by the bottom rotary switch (closest to the J2 connector).

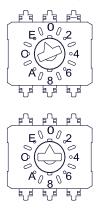


Figure 25 Model 100 Terminal Board Rotary Switches

4. Install the battery in the condulet and observe that the controller display starts and the unit will go through the boot-up sequence (Section 3.12).

#### **AC Operated Units**

Units that have a Transceiver, and come supplied with the AC/DC Converter need only have AC voltage applied to operate properly

1. Attach the mounting plate assembly to a pole with two U-Bolts secured through the 7/16" rectangle holes of the mounting plate base (Figure 23).

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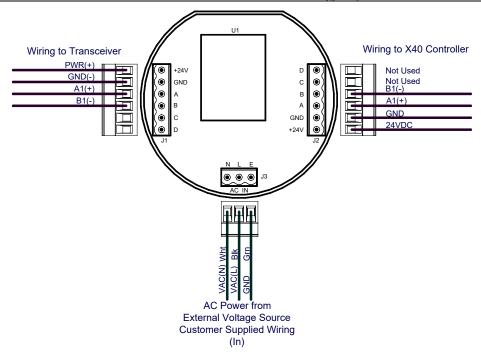


Figure 26 N7 AC/DC Converter Board Wiring with Transceiver

<u>^</u>

*CAUTION*: The cable used to connect to the terminals of the X40-32-N7 must be rated for a minimum of 105°C.

*ATTENTION:* Le câble utilisé pour se connecter aux bornes du X40-32-N7 doit être conçu pour un minimum de 105 °C.

2. Install AC power and I/O connections when the N7 is supplied with a J-Box and an AC/DC converter. Connect 100-240VAC input wiring to the J3 connector (labeled AC IN) of the converter board.

**NOTE:** The terminals on the **J3** connector are labeled **N** (neutral), **L** (line power) and **E** (earth ground).

**NOTE:** An optional Transient Protection board is available from Teledyne Detcon for use with external DC Supply. When using external DC power to power the controller the input power must be 11.5-30VDC.

3. After applying AC to the unit observe that the controller display starts and the unit will go through the boot-up sequence (Section 3.12).

#### **DC** Operated Units

1. For units that will be wired to an external power source connect the external power to the Transient Protection PCA '+' and '-' terminals. Voltage input must be between 11.5VDC and 30VDC.

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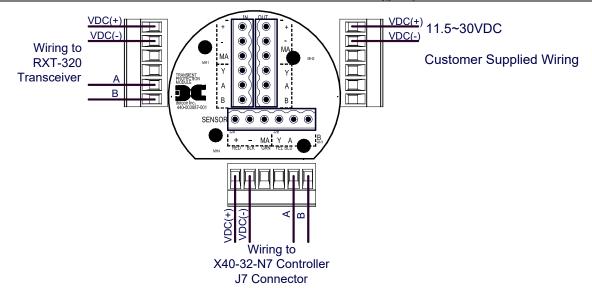


Figure 27 N7 DC Power Wiring with Transceiver

**NOTE:** An optional Transient Protection board is available from Teledyne Detcon for use with external DC Supply. When using external DC power to power the controller the input power must be 11.5-30VDC.

2. After applying power to the unit observe that the controller display starts and the unit will go through the boot-up sequence (Section 3.12).

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# 3. I/O Connections

#### 3.1 I/O Module Installation

**NOTE:** The X40-N4X enclosure with alarm strobe and or horn have a minimum of one RL-4 module installed to power the alarms. This RL-4 should not be removed.

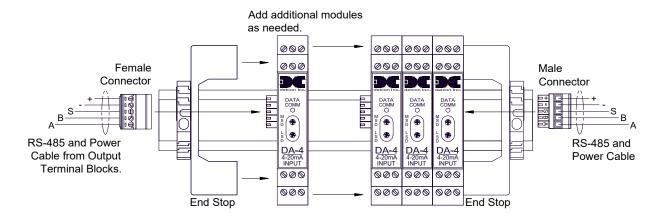


Figure 28 I/O Module Installation

I/O modules are mounted on an industry-standard 37.5 x 7.5 mm DIN rail (See Figure 28). Install the first I/O module at the end of the DIN rail nearest the male connector. Plug the male connector into the side of the module. Slide it all the way to the end stop. Add additional modules next to the first module. When installing additional I/O modules, make sure there is about 0.5 inch clearance on either side of the module and snap the module onto the DIN rail (the 0.5" spacing is to allow for connector clearance). Once the I/O module is snapped onto the DIN rail, slide it towards the adjacent module and assure that it firmly plugs into it. Connect the RS-485 and power female connector to the last module installed on the DIN rail. Secure the modules with an end stop.

**NOTE:** The male and female connectors must be plugged into modules on opposite ends of the DIN rail. If these connectors are not properly installed, communication with other RS-485 devices will not be possible.

**NOTE:** If no I/O modules are installed in the controller, the male connector must be plugged into the female connector for the RS-485 to communicate.

**NOTE:** For addressable I/O modules or Modbus<sup>TM</sup> sensors that are located remotely from the controller, General Cable Commodore (P/N ZO16P0022189) is recommended for serial and power connections.

## 3.2 Analog 4-20mA Sensor Inputs (DA-4)

Connect the 4-20mA gas sensors to DA-4 4-20mA input modules. The DA-4 modules provide power to any 2-wire or 3-wire field sensors, and receive standard 4-20mA signal inputs from the sensors Figure 29.

**NOTE:** The terminals on the DA-4 module are rated for a maximum of 30VDC. They are designed to accept solid or stranded wire between 12AWG and 24AWG.

**NOTE:** Analog sensors used with the X40 must supply 4mA for a zero reading and 20mA for a full scale reading. The sensors current output should be linear for readings between zero and full scale. Sensors that do not meet this requirement must not be used with the X40.

**NOTE:** External devices attached to the equipment must require a tool to access their wiring terminals to prevent unauthorized access.

**NOTE:** Hazardous live voltages of external devices attached to the DA4 must be isolated or disconnected prior to accessing the terminals of the external devices.

**NOTE:** All cable penetrations for analog sensor cables must be made in the bottom of the enclosure (See Figure 13). All penetrations must use a NEMA4 rated cable gland (Appleton P/N CG-2575 or equivalent) to prevent water ingress and restrict access to the internal circuits of the X40..

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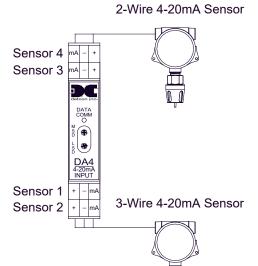


Figure 29 Model DA-4 4-20mA Input Module and 4-20mA Gas Sensor Connections

There are four 4-20mA inputs with each DA-4 module to support up to four sensors (See Figure 30). DA-4 modules can be installed on the DIN rail of the controller.

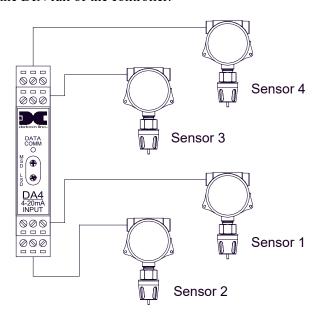


Figure 30 Model DA-4 4-20mA Input Module and 4-20mA Gas Sensors

Serially address each DA-4 module in hex using the two rotary switches on the front of the module labeled **MSD** (most significant digit) and **LSD** (least significant digit). Ensure that each DA-4 module has a unique Modbus<sup>TM</sup> address and is addressed within the range 01h-7Fh.

**NOTE:** DA-4 modules must be connected to the RS-485 Master Port, they must be addressed correctly within the range of 01h-7fh.

**NOTE:** The sensors must be powered on and outputting at least 1.8mA to be detected by the auto configure. If a sensor is in fault, its output will be 0mA and it will not be detected by the auto configure.

A DA-4 module connected properly to the controller will have a flashing DATA COMM LED to indicate a valid communication status and will provide the controller with a continuous reading of the sensor attached. All other information will need to be modified on the Channel Details screen for each channel corresponding to the appropriate DA-4 module.

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## 3.3 Dry Contact Inputs (DI-A

Relay contact outputs from field devices can be connected to Model DI-4 input modules. There are four relay contact inputs in each Model DI-4 module (See Figure 31). DI-4 modules can be installed on the DIN rail of the controller. DI-4 modules must be connected to the RS-485 Master Port.

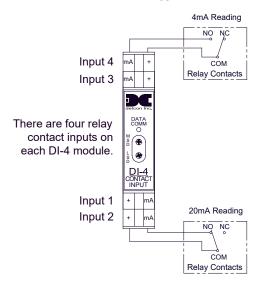


Figure 31 Model DI-4 Contact Input Module

**NOTE:** The terminals on the DI-4 module are rated for a maximum of 30VDC. They are designed to accept solid or stranded wire between 12AWG and 24AWG.

**NOTE:** External devices attached to the equipment must require a tool to access their wiring terminals to prevent unauthorized access.

**NOTE:** Hazardous live voltages of external devices attached to the equipment must be isolated or disconnected prior to accessing the terminals of the external devices.

**NOTE:** The cable penetrations for the dry contact inputs must be made in the bottom of the enclosure (See Figure 13). All penetrations must use a NEMA4 rated cable gland (Appleton p/n CG-2575 or equivalent) to prevent water ingress and restrict access to the internal circuits of the X40.

Serially address the module in hex using the two rotary switches on the front panel labeled MSD (most significant digit) and LSD (least significant digit). Ensure that each DI-4 module has a unique Modbus<sup>TM</sup> address and is addressed within the range 01h-7Fh.

**NOTE:** DI-4 modules must be connected to the RS-485 Master port, they must be addressed correctly in the range of 01h-7fh.

A DI-4 module connected properly to the controller will have a flashing DATA COMM LED to indicate a valid communication status and will provide the controller with a 4mA reading when the contact from the field device is open and a 20mA reading when the contact is closed for the corresponding channels. All other information will need to be modified on the Channel Details screen for each channel corresponding to the appropriate DA-4 module.

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## 3.4 Analog 4-20mA Outputs (AO-4)

There are four 4-20mA outputs in each Model AO-4 module (See Figure 32). These can be used as signal inputs to other control devices. AO-4 modules can be installed on the DIN rail of the controller.

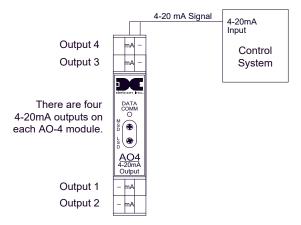


Figure 32 Model AO-4 4-20mA Output Module

**NOTE:** The terminals on the AO-4 module are rated for a maximum of 30VDC. They are designed to accept solid or stranded wire between 12AWG and 24AWG.

**NOTE:** External devices attached to the equipment must require a tool to access their wiring terminals to prevent unauthorized access.

**NOTE:** Hazardous live voltages of external devices attached to the AO4 must be isolated or disconnected prior to accessing the terminals of the external devices.

**NOTE:** The cable penetration for the analog outputs must be made in the bottom of the enclosure (See Figure 13). All penetrations must use a NEMA4 rated cable gland (Appleton p/n CG-2575 or equivalent) to prevent water ingress and restrict access to the internal circuits of the X40.

AO-4 modules provide a 4-20mA output equal to the current concentration reading reported to the controller for the associated channel. These concentration readings are communicated by the controller to the AO-4 modules using RS-485 Modbus<sup>TM</sup> RTU protocol. Therefore, each AO-4 module must have a unique Modbus<sup>TM</sup> address. Modules are serially addressed in hex using the two rotary switches on the module's front panel labeled MSD (most significant digit) and LSD (least significant digit). AO-4 modules must be connected to the RS-485 Master Port. The AO-4 modules must be addressed according to Table 2 AO-4 Modbus<sup>TM</sup> Addresses.

Module	Channel #	Decimal	Hex	Module	Channel #	Decimal	Hex
1	1 2 3 4	161	A1	5	17 18 19 20	165	A5
2	5 6 7 8	162	A2	6	21 22 23 24	166	A6
3	9 10 11 12	163	А3	7	25 26 27 28	167	A7
4	13 14 15 16	164	A4	8	29 30 31 32	168	A8

Table 2 AO-4 Modbus<sup>TM</sup> Addresses

**NOTE:** The AO-4 modules must be connected to the RS-485 Master Port and addressed correctly in the range of A1h-A8h.

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An AO-4 module connected properly to the controller will have a flashing DATA COMM LED to indicate a valid communication status and will provide a continuous output mA reading that corresponds directly to the sensor attached. If the controller does not detect an AO-4 module, the blue LED (Fault) will start flashing and COMM ERROR will be displayed on the AO-4 group page.

**NOTE:** The AO-4 modules must be connected to the RS-485 Master Port and addressed correctly in the range of A1h-A8h.

## 3.5 Alarm Relay Outputs (RL-4)

There are four (4) Form C Single Pole Double Throw (SPDT), 5 Amp relays in each Model RL-4 module. Each relay in the module is assigned specifically to one alarm. Relay 1 is assigned to Alarm 1, relay 2 is assign to Alarm 2, relay 3 is assigned to Alarm 3, and relay 4 is assigned to Fault. These can be used to control (fire) annunciating devices or as signal inputs to other control devices. Connections to the relay contacts of the RL-4 module are shown in Figure 33 and are labeled C (Common), NO (Normally Open) and NC (Normally Closed). Note that the 5 Amp rating of the relay contact should not be exceeded. RL-4 modules are installed on the DIN rail of the controller.

There are four Form C, Single Pole Double Throw (SPDT), 5 Amp relay contacts in each RL-4 module. Each relay in the module is assigned to one alarm as follows:

NOTE

- Relay 1 is assigned to Alarm 1
- Relay 2 is assign to Alarm 2
- Relay 3 is assigned to Alarm 3

Relay 4 is assigned to Fault

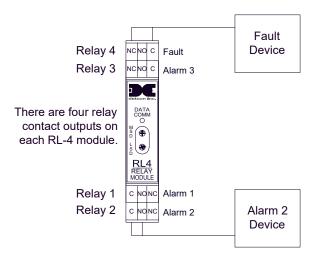


Figure 33 Model RL-4 Relay Output Module

**NOTE:** The current ratings of the relay contacts, 5A @ 30VDC, 5A @ 250VAC and 5Amp rating should not be exceeded. Wire attached to the RL4 terminals must be safety approved and rated for at least 5A.

**NOTE:** External devices attached to the RL4 outputs must require a tool to access their wiring terminals to prevent unauthorized access.

**NOTE:** The cable penetration for the relay outputs must be made in the bottom of the enclosure (See Figure 13). All penetrations must use a NEMA4 rated cable gland (Appleton p/n CG-2575 or equivalent) to prevent water ingress and restrict access to the internal circuits of the X40.

Serially address the module in hex using the two rotary switches on the front panel labeled MSD (most significant digit) and LSD (least significant digit). Ensure that each RL-4 module has a unique Modbus<sup>TM</sup> address. Set the relay Modbus<sup>TM</sup> address for each RL-4 module in accordance with Table 3.

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Bank	Module	Decimal	Hex
Bank1	1	128-129	80-81
Bank2	2	130-131	82-83
Bank3	3	132-133	84-85
Bank4	4	134-135	86-87
Bank5	5	136-137	88-89
Bank6	6	138-139	8A-8B
Bank7	7	140-141	8C-8D
Bank8	8	142-143	8E-8F

Table 3 RL-4 Relay Modbus™ Addresses

If the N4X unit is ordered with an integral alarm strobe, it will be connected to the **Alarm 1** connector of the first RL-4 installed in the enclosure. The RL-4 is configured to Bank1, Alarm1, but can be reconfigured by the user (refer to Section 5.2.4).

**NOTE:** The RL-4 modules must be connected to the RS-485 Master Port, and must be addressed correctly in the range of 80h-8Fh.

A RL-4 module connected properly to the controller will have a flashing DATA COMM LED to indicate a valid communication status and will provide the controller with 4 user assignable relay outputs that can be used to drive external annunciator devices. If the controller does not detect a configured and assigned RL-4 module, the blue LED (Fault) will start flashing and a comm error will be displayed on the RL-4 group page.

#### 3.6 RS-485 Serial Gas Sensors

RS-485 Serial Sensors will communicate directly with the X40 via Modbus<sup>TM</sup>. Connect the five wires of the Modbus<sup>TM</sup> capable sensor to the Modbus<sup>TM</sup> DIN rail mounted terminal blocks labeled **RS-485 MASTER** and **VDC Out** (Figure 34).

**NOTE:** The only Modbus<sup>TM</sup> capable Teledyne Detcon sensors that may be used with the X40 are Model 100, Model 600 and Model 700 series.

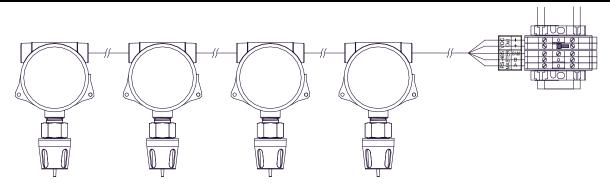


Figure 34 Modbus<sup>TM</sup> Gas Sensor Connections

**NOTE:** The only Modbus<sup>TM</sup> capable Teledyne Detcon sensors that may be used with the X40 are Model 100, Model 600 and Model 700 series.

Ensure that each serial sensor is assigned a unique Modbus<sup>TM</sup> address and within the range 01h-7Fh. Connect the sensors in a daisy-chained series to the other RS-485 sensors.

**NOTE:** The only Modbus<sup>TM</sup> capable Teledyne Detcon sensors that may be used with the X40 are Model 100, Model 600 and Model 700 series.

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## 3.7 Wireless RXT-320 Modbus<sup>TM</sup> Devices and CXT-320 Sensors

Teledyne Detcon offers a wide range of wireless sensors and field devices for use with the X40 wireless option if selected. Devices such as alarm stations, remote displays and various sensor types are available and able to communicate wirelessly using transceivers that operate at 2.4GHz and conform to non-licensed radio frequency appliance usage around the world. Refer to these devices specific manuals for more detailed information.

For proper communication, wireless devices must have a unique Modbus<sup>TM</sup> address and must reside on the same RF channel/Network ID as the wireless transceiver of the X40 Master Ports Transceiver. The assigned Modbus address for the serial sensor does not necessarily correspond to the channel number in the controller. The Modbus address assigned for wireless sensors does not necessarily determine the channel number the controller will assign it to. (Modbus<sup>TM</sup> addresses are hexadecimal. Channels numbers are decimal. A conversion chart can be found in Section 11.2 Hexadecimal Table.) The controller will acknowledge Wireless sensors addressed between 01h and 20h. The controller will acknowledge alarm stations with addresses of 80 through 8Fh.

**NOTE:** Each wireless device in the network must have a unique Modbus address. All wireless devices in the network must reside on the same RF channel/Network ID.

## 3.8 RXT-320 Wireless Transceiver Analog Inputs

The RXT-320 wireless transceiver provides two 4-20mA inputs that can be used to monitor 4-20mA devices. The input values are continuously read and stored in two separate registers accessible through Modbus at the Modbus address assigned to the transceiver enabling analog inputs to be configured automatically with the Auto Configure function of the MCX-32.

The two 4-20mA inputs are accessible when an RXT-320 transceiver is connected to Teledyne Detcon's optional Model 100 Terminal Board. 'AIN1' on connector J8 corresponds to analog input one and 'AIN2' on connecter J7 corresponds to analog input two. During an Auto Configure, a 4-20mA signal must be active on these inputs in order for the controller to recognize them.

**NOTE:** If the RXT-320 is used for Analog inputs the Device Type in the configuration must be set properly for the X40 Controller to recognize the RXT as an analog input device.

**NOTE:** If only one analog input is to be used, it is recommended to interface the mA output of the sensor to AIN1.

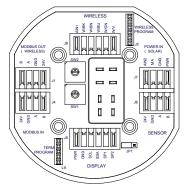


Figure 35 Model 100 Terminal Board

The 4-20mA signals from the RXT-320 transceivers are communicated wirelessly to the controller using RS-485 Modbus<sup>TM</sup> RTU protocol therefore each wireless transceiver must have a unique Modbus<sup>TM</sup> address. Wireless transceivers are serially addressed in hex using the two rotary switches on the transceiver's smart terminal board (Figure 35). SW2 corresponds to the most significant digit (MSD) and SW1 corresponds to the least significant digit (LSD). Each analog input has a specific channel assigned in the controller and is dependent on the Modbus address set from the smart term board. All other information will need to be modified on the Channel Details screen for each channel corresponding to the appropriate RXT-320 analog input.

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# 3.9 RXT-320 Wireless Transceiver Analog Inputs

Teledyne Detcon offers a SmartWireless® CXT Site Sentinel Slave Controller which can be configured to the X40 controller if the wireless option is selected. The CXT Sentinel Slave Controller is a wireless RXT320 device that transmits data from up to four wired analog sensors back to the X40 wirelessly using radios that operate at 2.4GHz and conform to non-licensed radio frequency appliance usage around the world. Refer to the SmartWireless® CXT manual for more detailed information. The CXT Slave Controller's wireless transceiver must reside on the same RF channel/Network ID as the wireless transceiver of the X40. RF channel/Network ID selection is accomplished using the SW1 rotary switch. The CXT Slave Controller address must be unique, and should be set between 01h and 7Fh.

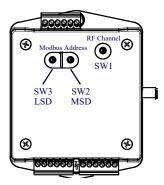


Figure 36 CX/CXT Wireless Transceiver

The CXT Slave Controller has the option of employing a Relay Output PCA. The relay output PCA of the CXT Slave Controller is controlled by the CXT Slave Controller, and is not, and should not be considered as part of the X40 Alarms. The X40 has no control over the CXT Slave Controller's relay output PCA. This Relay Output PCA can only be set according to the Slave Controller, and can only be used to control alarms that are set up by, and attached to the Slave Controller.

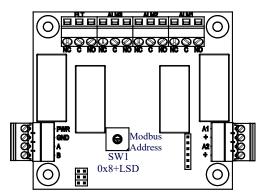


Figure 37 CX/CXT Relay Output PCA

The analog input card of the CXT Slave Controller functions similar to a DA4 module. It is found mounted under the relay output PCA.

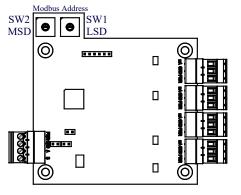


Figure 38 CX/CXT Analog Input PCA

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The 4-20mA signals from the sensors are communicated by the CXT Slave Controller to the X40 controller using RS-485 Modbus<sup>TM</sup> RTU protocol. The analog input PCA is serially addressed to the CXT Slave Controller in hex using the two rotary switches labeled SW2 MSD (most significant digit) and SW1 LSD (least significant digit). The analog input PCA should have an address of 01h to interface properly with the CXT Slave Controller. The CXT Slave Controller then communicates with the X40 Controller, and the CXT Slave Controller then acts as the controlling device to the analog input PCA.

**NOTE:** During Auto Configure, only CXT Slave Controller inputs with an active 4-20mA signal will be recognized.

### 3.10 SmartWireless® CX Sentinel Sensor Station

Teledyne Detcon offers a SmartWireless® CX Sensor Station which can be configured to the X-40 controller if the wireless option is selected. The CX Sensor Station is a wireless RXT320 device that transmits data from up to four wired analog sensors back to the X-40 using radios that operate at 2.4GHz and conform to non-licensed radio frequency appliance usage around the world. Refer to the CX Sensor Station manual for more detailed information. The CX Sensor Station's wireless transceiver must reside on the same RF channel/Network ID as the wireless transceiver of the MCX-32 corresponding to the correct port for the controller. RF channel/Network ID selection is accomplished using the SW1 rotary switch. The CX Sensor Station also consists of three different Modbus components that must be addressed accordingly for proper communication. These three Modbus components are located in the CX wireless transceiver, the CX relay output PCA and the CX analog input PCA, each requiring unique Modbus addressing as follows:

The wireless transceiver of the CX Sensor Station should be addressed between 01h and 20h when configured to the RS-485 Master Port. Wireless transceivers are serially addressed in hex using the two rotary switches on the transceiver (Figure 36). The SW2 rotary switch corresponds to the most significant digit (MSD) and the SW3 rotary switch corresponds to the least significant digit (LSD).

The relay output PCA of the CX Sensor Station functions similar to an RL4 module and needs to be addressed and configured as such. The most significant digit (MSD) for the relay output PCA is hard coded to a hex value of 8 so only the least significant digit (LSD) must be set using the SW1 rotary switch (Figure 37).

**NOTE:** The MSD for the relay output PCA is hard coded to a hex value of 8 so only the LSD must be set. Addressing criteria is the same as RL4's and Alarm Stations and will be seen as an RL4 by the Controller.

The analog input card of the CX Sensor Station functions similar to a DA4 module. It is found mounted under the relay output PCA.

The 4-20mA signals from the sensors are communicated by the CX Sensor Station to the controller using RS-485 Modbus<sup>TM</sup> RTU protocol. The analog input PCA is serially addressed in hex using the two rotary switches labeled SW2 MSD (most significant digit) and SW1 LSD (least significant digit). Refer to Figure 38. Each CX Site Sentinel will have four channels reserved based on its Modbus address with each channel corresponding to each of its four inputs. The Modbus Addresses should be set between 01h and 7Fh.

**NOTE:** During Auto Configure only CX Sensor Station inputs with an active 4-20mA signal will be recognized..

# 3.11 General Installation Wiring Notes

- ❖ Follow generally accepted guidelines for RS-485 serial networks. Do not wire I/O Modules and/or Modbus™ gas sensors in long-distance 'T-Tap' configurations. Instead, use a "daisy-chain" wiring scheme.
- Use Teledyne Detcon Recommended cabling whenever possible.
  - General Cable Commodore P/N ZO16P0022189 is recommended for a single cable providing serial communications and power.
- ❖ Ground the cable shielding at the Model MCX-32 controller *only*. Other points of grounding may cause a ground loop, and induce unwanted noise on the RS-485 line, which in turn may disrupt communications.
- ❖ For wireless installations, verify that all devices in the wireless network reside on the same RF channel as transceivers will only respond to other transceivers with the same RF channel.

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- ❖ If multiple wireless networks are implemented, each wireless network must exist on a separate RF channel in order to avoid cross talk and interference between networks.
- Any slave device near an elevated antenna needs to be at least as far from the antenna as the antenna is high. For example, if the antenna is 20ft. high, then the nearest slave device should be at least 20 ft. away.

# 3.12 Initial Start-Up

**NOTE:** Ensure that power is turned off to the X40 before installing or removing the SD card.

- 1. Verify that all the wiring connections and external devices are installed correctly before applying power to the controller.
- 2. Verify that all Modbus<sup>TM</sup> devices have unique Modbus<sup>TM</sup> address, and are addressed correctly.
- 3. Apply the desired power option to the X40. For N1 and N4 units, ensure that the Disconnect Terminal Blocks are closed. The controller will power up once power is applied.
- 4. Verify normal operation once power is applied to the unit. The unit will cycle through the following:
- Boot up and display the company name, model, firmware version and COMM ports available.
- Proceed to poll Modbus<sup>TM</sup> addresses of any attached devices.
- The LCD will then refresh and display the next eight channels and so on until the LCD cycles back to the first eight channels and repeats the process.

**NOTE:** Data logging does not occur during the first 10 minutes after power-up of the unit. This delay allows the sensors time to stabilize, so that inaccurate or faulty readings will not be logged during this stabilization period.

5. Apply test gas to each sensor connected to the X40. Verify that the correct alarm outputs are activated when gas is applied. If AO-4 modules are installed, the current output for each channel should also be verified.

# 4. I/O Connections

**NOTE:** Ensure that power is turned off to the X40 before installing or removing the SD card.

- 1. Install the SD card in the SD slot (J9) on the back of the controllers PCA before the controller is powered up.
- 2. The controller will notify the user if a successful installation of the card was achieved upon power up.
- 3. The controller will automatically format the card and create the necessary files for data logging. Refer to Section 5.2.8 for more information regarding the data logging feature.

**NOTE:** Data logging does not occur during the first 10 minutes after power-up of the unit. This delay allows the sensors time to stabilize, so that inaccurate or faulty readings will not be logged during this stabilization period.

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# 5. System Configuration

# 5.1 X40 Controller Setup

1. The PROG switch is used to enter the menu mode of the unit by swiping a programming magnet over the corresponding marker (⊗). Upon entering the menus, all Modbus™ polling stops, sensor values are not read and alarm outputs are not updated.

**NOTE:** If the X40 is in alarm when the user enters the menu, it will stay in alarm until they exit the menu.

1. Upon entering the MAIN MENU, the LCD will display the following:

# MAIN MENU AUTO CONFIGURE SYSTEM

- 2. Use the down arrow "↓" switch to move to the next menu item or use the up arrow "↑" switch to move to the previous menu item by swiping the programming magnet over the corresponding markers. Swiping the **PROG** switch again will return the unit to normal operation.
- 3. Swipe the **ENTER** marker when the appropriate menu item is located to enter the menu.

# 5.2 Menu Functions

The Main Menu and consists of seven menu items:

- 1. Auto Configure System
- 2. Setup Channel Data
- 3. Set Channel Alarms
- 4. Set Relay Function
- 5. Inhibit & Alarm Test Mode
- 6. System Diagnostics
- 7. Time and Date
- 8. View TWA & Peak

### **Auto Configure System**

- 1. Ensure that the addresses on all modules and sensors are correctly set (Section 3.0).
- 2. Verify that all 4-20mA inputs are turned on. (Note: Only currents above 1.8mA will be detected.)
- 3. Upon entering Auto Configure menu, the LCD will display:

# CONFIGURATION SUMMARY

CHANNELS:##

AO4S:## WIRELESS TRANSCEIVER WTS:## RL4/ALARM STATION COUNT:## [RUN SYSTEM AUTO CONFIGURE]

4. Swipe the ENTER marker to initiate the search. The X40 controller will perform an incremental search for available 700/100 and 600 serial sensors starting with Modbus<sup>™</sup> address 01h and analog inputs with a minimum current of 1.80mA.

**NOTE:** All sensors and modules must be powered on to be detected correctly.

**NOTE:** The channel tags for the analog inputs will be set to "PPM H2S" by default. These can be changed in the Utilities menu.

**NOTE:** The channel tags for detected serial sensors will be set to gas type and units of the sensor detected by default. These can be changed through the Utilities menu.

**NOTE:** A swipe of the PROG marker while in search mode will abort the search and restore the previous configuration. Any devices found up to that point will not be saved.

5. The search will continue until Modbus<sup>TM</sup> address 7Fh is reached or the search is terminated by swiping the 'ENTER' marker which will save the current found configuration. When all of the connected sensors are identified, swipe 'ENTER' to begin detecting RL4 modules beginning with Modbus<sup>TM</sup> address 80h.



**NOTE:** Once all of the attached sensors are identified, swipe the ENTER marker to move on to the next stage (RL4 search). Each address that is not responding will take an additional two seconds to time out.

- 6. The search will continue until Modbus<sup>TM</sup> address 8Fh is reached or the search is terminated by swiping the 'ENTER' marker which will save the RL4 modules. When all of the connected RL4s are identified, swipe 'ENTER' to begin detecting AO-4s with Modbus<sup>TM</sup> address A1h.
- 7. The search will continue until Modbus<sup>™</sup> address A8h is reached or the search is terminated by swiping the ENTER marker which will save the AO-4 modules. When all of the connected AO-4s are identified, swipe 'ENTER' to begin detecting wireless radio modules starting with Modbus<sup>™</sup> address 01h.
- 8. The search will continue until Modbus<sup>™</sup> address 7Fh is reached or the search is terminated by swiping the ENTER marker which will save the wireless radio modules found.

**NOTE:** A swipe of the PROG marker while in search mode will abort the search and restore the previous configuration. Any devices found up to that point will not be saved.

# **Setup Channel Data**

1. Upon entering this menu, the LCD will display:

CHANNEL 1 DATA: DECIMAL POINT:

SLAVE ID: RANGE: DEVICE TYPE: TYPE:

ANALOG INPUT: RL4 BANK CNT:

- 2. A flashing cursor will appear on SLAVE ID. Swiping the magnet over:
  - The markers of the up or down arrows will move the flashing cursor to the desired function.
  - The ENTER marker will select the function indicated by the flashing cursor
  - The markers of the up or down arrows will change the value.
  - The ENTER marker will save the selected value and return to the flashing cursor.

If there is more than one channel, a swipe of the down arrow marker while the flashing cursor is on RL4 BANK CNT will scroll the display to the next channel allowing for its configuration. To return to the previous channel, a swipe of the up arrow marker should be performed while the flashing cursor is on SLAVE ID.

- 3. SLAVE ID is detected during the X40 auto-configuration process and cannot be changed by the user.
- 4. DEVICE TYPE is detected during the X40 auto-configuration process and cannot be changed by the user.
- 5. If the device type is "DA4", then ANALOG INPUT indicates the DA4 input associated with the channel. If the device type is something other than "DA4", this field will read "—".
- 6. DECIMAL POINT indicates the number of places in the gas reading to the right of the decimal point. This value cannot be changed by the user.
- 7. RANGE is the range of the sensor attached to the channel. If the device type is "DA4", this value can be changed by the user. If the device type is something other than "DA4", this value is detected during auto-configuration and cannot be changed by the user
- 8. TYPE is the user entered name for the channel. It can be up to 9 characters long.
- 9. The RL4 banks assigned to the channel can be set using RL4 BANK CNT. Swiping ENTER on this field will show the RL4 banks assigned to this channel. If a number is displayed, then the bank is assigned to the channel. If "-" is displayed, then the bank is not assigned to the channel. The user can move between RL4 banks using down arrow marker. Swiping the up arrow marker on a bank will allow the user to toggle the bank on and off. Swiping ENTER marker will save the values and return to the Setup Channel Data menu.

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#### **Set Channel Alarm**

The Set Channel Alarms menu allows configuration of each channel's alarms. The information to be configured is the;

- ALM1 LEVEL,
- ALM1 ASCENDING, •
- ALM2 LEVEL,
- ALM2 ASCENDING,
- ALM3 LEVEL, and
- ALM3 ASCENDING.
- 1. Upon entering this menu, the LCD will display:

**CHANNEL 1 ALARMS: ALM2 LEVEL:** ## **ALM2 ASCENDING: X** ALM1 LEVEL: **ALM3 LEVEL: ALM1 ASCENDING: X** ALM3 ASCENDING: X

- 2. A flashing cursor will appear on ALM1 LEVEL. Swiping the magnet over:
  - The markers of the up or down arrows will move the flashing cursor to the desired function.
  - The ENTER marker will select the function indicated by the flashing cursor
  - The markers of the up or down arrows will change the value.
  - The ENTER marker will save the selected value and return to the flashing cursor.
- 3. If there is more than one channel, a swipe of the down arrow marker while the flashing cursor is on ALM3 ASCENDING will scroll the display to the next channel allowing for its configuration. To return to the previous channel, a swipe of the up arrow marker should be performed while the flashing cursor is on ALM1 LEVEL.
- 4. Ensure that the gas alarm relay (if not being used) has a setting of 0 to make it inactive.

**NOTE:** Any channels that are in alarm or fault will not display the device tag on the main display.

**NOTE:** If the channel range is changed, then the alarm set points must be re-entered.

#### **Set Channel Alarm**

1. Upon entering this menu, the LCD will display:

**FAULT RELAY SETUP: BANK 1** LATCHING:X **ENERGIZED:X** SILENCEABLE:X

Relays are displayed in the following order:

- **FAULT** NOTE
  - ALARM1
  - ALARM2
  - ALARM3
- 2. A flashing cursor will appear on LATCHING for Bank1. Swiping the magnet over:
  - The markers of the up or down arrows will move the flashing cursor to the desired function.
  - The ENTER marker will select the function indicated by the flashing cursor. •
  - The markers of the up or down arrows will change the value.
  - The ENTER marker will save the selected value and return to the flashing cursor.
  - The down arrow marker while the flashing cursor is on SILENCEABLE for Bank1 will scroll the display to the next relay allowing for its configuration.
  - The up arrow marker to return to the previous relay while the flashing cursor is on LATCHING for Bank1.

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**NOTE:** By default, each sensor found during the auto configuration will be assigned to all eight relay banks. This setting can be changed through the utilities menu.

- 3. Repeat Step 2 for the remaining banks containing three alarms and a fault.
- 4. Ensure that all four relay outputs in all eight banks are set-up to account for the following three settings (Section 1.7). The values selected can be either Y (Yes) or N (No).
  - Latching or Non-Latching
  - Energized or De-Energized
  - Silenceable or Non-Silenceable

**NOTE:** It is generally recommended to set the FAULT relay as energized so that it will trip upon loss of power.

**NOTE:** The FAULT condition is assigned to the FAULT relay as a standard. It cannot be disengaged in the configuration of the controller. The Main Display will show IN FAULT for any channel that is in fault.

### **Inhibit and Alarm Test Mode**

Inhibit mode permits testing of sensors while preventing alarms from being activated. Alarm test mode permits testing of the attached alarm devices without applying gas to the sensors

1. Upon entering this menu, the LCD will display:

INHIBIT & ALARM TEST MODE
INHIBIT MODE: | ALARM TEST MODE:
#:## |
START | OFF

- 2. These values can be changed by swiping the magnet over the markers of the up or down arrows to move the arrow prompt "→" to the desired function. A swipe over:
  - The ENTER marker will select the function indicated by the arrow prompt "→".
  - The markers of the up or down arrows will change the value.
  - The ENTER marker will save the selected value.
- 3. Activate inhibit mode by entering the timer value in minutes and seconds (0-60 minutes).
- 4. Select **START** and all relay outputs on the network will be disabled until the timer reaches 0 or is manually stopped by the user by turning off the inhibit mode.
- 5. Activate alarm test mode to verify that connected alarm devices are functioning properly by swiping the magnet over the markers. All channels will simultaneous go from 0 to full scale in 5% increments. When they reach full scale they will return to 0 in 5% increments. This will continue indefinitely until alarm test mode is turned off.
- 6. Verify that the relays fire according to their configuration as the readings cross their respective alarm set points.

### **System Diagnostics**

The System Diagnostics menu performs function tests for the following:

- LCD display,
- Panel LED's,
- External reset switch,
- · Relays, and
- Modbus<sup>TM</sup> interface.

Upon entering this menu, the X40 controller will automatically initiate a function test that displays every pixel LCD display. The controller then performs a function test of the LED drivers by activating all four LED's. After the LED test, the controller initiates a test for the external reset switch which lets the user know when the reset switch is pressed.

The user will be prompted:

1. To "press (swipe) enter key (marker) to continue" which will initiate the relay driver test and the controller will then reset all the relays and turn on the alarm 1 relay.

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- 2. To "press (swipe) any key (marker)" which will turn on the alarm 2 relay.
- 3. To "press any key" and the alarm 3 relay will be turned on.
- 4. To "press any key" and the fault relay will be turned on.
- 5. To "press any key" and all the relays will be reset.
- 6. Connect COMM1 (master) to COMM2 (slave) for a Modbus<sup>TM</sup> loop back test at different baud rates and "press any key" to continue or swipe any marker to stop the test.

**NOTE:** When performing the Modbus<sup>TM</sup> loop back test, the loop back cable should be installed between the **COMM1** (Master) port and the **COMM2** (Slave) port. Disconnect all other external Modbus<sup>TM</sup> interfaces from the loop and bypass any installed modules.

### **System Diagnostics**

1. Upon entering this menu, the LCD will display:

### TIME AND DATE:

##:##:## | ##:##:## [TIME] | [DATE]

- 2. Verify that **[TIME]** is selected and swipe the magnet over the ENTER marker to enter the SET TIME menu.
- 3. Swipe the magnet over the markers of the up or down arrows to move the arrow prompt "→"to the desired field.
- 4. A swipe over the ENTER marker will select the field indicated by the arrow prompt "→" and the value can be changed by swiping over the markers of the up or down arrows.
- 5. Another swipe over the ENTER marker will save the selected value.
- 6. Once the desired values have been set, move the arrow prompt to "Update Time" and swipe the ENTER marker to update the time with the changes entered.
- 7. Swipe the magnet over the marker of the down arrow and verify [DATE] is selected.
- 8. Swipe the magnet over the ENTER marker to enter the SET DATE menu.
- 9. Swipe the magnet over the markers of the up or down arrows to move the arrow prompt to the desired field.
- 10. A swipe over the ENTER marker will select the field indicated by the arrow prompt and the value can be changed by swiping over the markers of the up or down arrows.
- 11. Another swipe over the ENTER marker will save the selected value.
- 12. Once the desired values have been set, move the arrow prompt to "Change Date" and swipe the ENTER marker to update the date with the changes entered.
- 13. A swipe of the PROG marker at any time while setting the time or date will escape out of the current menu with no changes saved.

#### View TWA and Peak

- 1. Verify that a secure digital (SD) memory card is installed in the SD slot of the X40 controller board (J9).
- 2. Upon entering this menu, the user can view the data recorded from the SD card and is displayed as:

<File Name>:

MM/DD/YY, HH:MM:SS, Channel #, TWA #, PEAK #

**Example:** 

TWA P08.CSV:

05/17/11,23:00:09,17, 51, 100

The sensor readings are continuously logged to the SD card. This data can also be viewed by removing the SD card and inserting it in a laptop using the Teledyne Detcon Log File Viewer application. Refer to the Teledyne Detcon Log File Viewer instruction manual for detailed information.



# 6. Modbus™ Slave Communication Port

A Modbus<sup>TM</sup> RTU master can poll the slave port on the X40 allowing the Modbus master to remotely monitor the status of the X40. If multiple X40s are being used on a single Modbus<sup>TM</sup> network, each controller must be set to a different device address.

The Modbus Slave Port communicates at 9600 baud, eight bits, no parity, and one stop bit (8-N-1). The minimum inter-poll delay is 150ms and the response timeout should be 2000ms at a minimum. The maximum recommended poll rate is once per second.

# 6.1 Menu Functions

Table 4 X40 Register Map

Channel #	Register	Description	Channel #	Register	Description
Channel 1	40000	Reading	Channel 17	40032	Reading
Chamici	40001	Status		40033	Status
Channel 2	40002	Reading	Channel 18	40034	Reading
Charmer 2	40003	Status	Charmer 10	40035	Status
Channel 3	40004	Reading	Channel 19	40036	Reading
Charmer 5	40005	Status	Charmer 19	40037	Status
Channel 4	40006	Reading	Channel 20	40038	Reading
Charmer 4	40007	Status	Charmer 20	40039	Status
Channel 5	40008	Reading	Channel 21	40040	Reading
Charmer 5	40009	Status	Onariner 21	40041	Status
Channel 6	40010	Reading	Channel 22	40042	Reading
Charmero	40011	Status	Charmer 22	40043	Status
Channel 7	40012	Reading	Channel 23	40044	Reading
Charmer 7	40013	Status	Charmer 25	40045	Status
Channel 8	40014	Reading	Channel 24	40046	Reading
Charmero	40015	Status	Onarrici 24	40047	Status
Channel 9	40016	Reading	Channel 25	40048	Reading
Charmer 9	40017	Status	Charmer 25	40049	Status
Channel 10	40018	Reading	Channel 26	40050	Reading
Charmer 10	40019	Status	Charmer 20	40051	Status
Channel 11	40020	Reading	Channel 27	40052	Reading
Charmer 11	40021	Status	Charmer 27	40053	Status
Channel 12	40022	Reading	Channel 28	40054	Reading
Onarrici 12	40023	Status	Onariner 20	40055	Status
Channel 13	40024	Reading	Channel 29	40056	Reading
Onarrici 13	40025	Status	Onariner 29	40057	Status
Channel 14	40026	Reading	Channel 30	40058	Reading
	40027	Status	Onamie 30	40059	Status
Channel 15	40028	Reading	Channel 31	40060	Reading
Onamie 13	40029	Status	Onamier 51	40061	Status
Channel 16	40030	Reading	Channel 32	40062	Reading
Charmer 10	40031	Status	Onariner 32	40063	Status

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# **Reading Register**

Current gas reading of the channel assigned to the register.

# **Status Register**

Bit 0	Alarm 1	0 = No Alarm	1 = In alarm 1		
Bit 1	Alarm 2	0 = No Alarm	1 = In alarm 2		
Bit 2	Alarm 3	0 = No Alarm	1 = In alarm 3		
Bit 3	Fault	0 = No Fault	1 = Sensor/Alarm Fault		
Bit 4 <sup>1</sup>	Cal	0 = Normal Operation	1 = In Cal		
Bit 5	Comm Error	0 = Normal Operation	1 = Communication Error		
Bit 6 &	Decimal Point	00 = No Decimal Point(No Divisor)	10 = 2 Decimal Point (Divisor of 100)		
Bit7 <sup>1</sup>	Decimal Point	01 = 1 Decimal Point ( Divisor of 10)	11 = Undefined (Default to No Decimal Point)		
Bit 8	Smart Battery Pack	0 = No Smart Battery Pack	1 = Smart Battery Pack		
Bit 9	Battery Error	0 = No Battery Error	1 = Battery Error		
Bit 10	Low Battery	0 = No Low Battery	1 = Low Battery		
Bit 11	Not Used				
Bit 12	Wireless Network Type	0 = 320	1 = 300		
		000 = Channel Disabled	100 = Repeater <sup>5</sup>		
Bits	Type	001 = CXT Sensor	101 = Sensor		
13-15	Type	010 = Alarm Station	110 = Undefined (Sensor)		
		011 = SmartHMI <sup>5</sup>	111 = Undefined (Sensor)		

<sup>&</sup>lt;sup>1</sup> These bits are only active for sensor devices



# 7. Remote Alarm Reset/Acknowledge Switch Installation

- 1. Mount the reset switch on the bottom or side of the NEMA 4X enclosure. For the other enclosure types, the switch must be mounted externally such as in the bottom of a J-Box.
- 2. Standard Momentary Pushbutton Switch
  - a. The standard reset switch should be a Normally Open, Momentary Closed switch that is rated for the area of installation.
  - b. Connect the Remote Alarm Reset/Acknowledge switch to the terminals of the terminal block labeled "REMOTE RESET" for the N1P and N4X controllers (Figure 39). For the N7 controller, connect the switch to the terminals "SW" on connector J7 (Figure 40) Once installed, pushing the switch will execute the reset/acknowledge function.



Figure 39 N1P & N4X Remote Switch Input

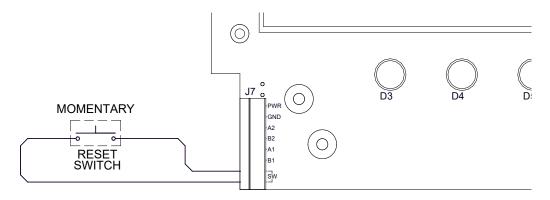


Figure 40 N7 Remote Switch Input

- 3. Teledyne Detcon Class I Division I Switch
  - a. Connect the red wire to the PWR or +24V terminal
  - b. Connect the black wire to the GND or terminal
  - c. Connect the purple wire to the SW connection nearest the B1 terminal (Figure 41)

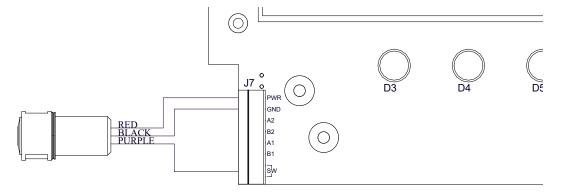


Figure 41 Teledyne Detcon C1D1 Switch Connections

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# 8. Troubleshooting Guide

# Unit will not power up

Verify correct AC or DC voltage selection.

Verify correct VAC and VDC powering configuration.

### Relays are not firing

Verify that the alarm relays are configured properly.

### Alarms on constantly

Ensure that no channels are set to ascending or descending incorrectly.

# Alarm Firing causes unit to "Lock Up"

Verify that the alarm annunciator current draw does not exceed the on-board power supply limits. Replace with external power supply if necessary.

Contact the Teledyne Detcon Service Department for further troubleshooting assistance at 713-559-9200.

# 8.1 Replacement of the display PCA in NEMA7 units

The NEMA 7 units come with the display assembly PCA P/N 500-005142-100.

- 1. Remove the NEMA7 enclosure cover from the enclosure and set aside.
- 4. Unplug the connector to J7 of the Display PCA.
- 5. Remove the screws holding the PCA to the enclosure base, and remove the PCA completely.
- 6. Install the new PCA in the enclosure using the screws removed above
- 7. Ensure that the connector is wired correctly according to figure below.
- 8. Re-install the cove on the enclosure.

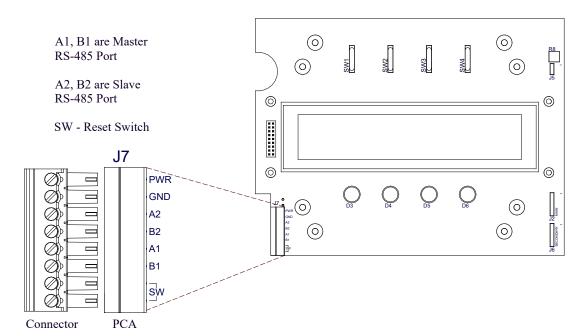


Figure 42 NEMA 7 Display Assembly PCA



# 8.2 Replacement of the display PCA in NEMA7 units

The NEMA4 enclosures come with a 'Drop-In' Display Assembly (P/N 949-005142-200)

- 1. Unplug the connector from J7 on the Display Assembly.
- 2. Remove the 10 Hex-Head bolts holding the Display Assembly to the cover of the enclosure
- 3. Replace the Drop-In Display Assembly on the enclosure cover, and replace the 10 Hex-Head Bolts.
- 4. Ensure that gasket is placed between the Drop-In Display Assembly and the cover.
- 5. Tighten the bolts to secure the Drop-In Display Assembly in place.
- 6. Reconnect the connector to J7 on the display.
- 7. Check the wiring going to the Drop-In Assembly. The correct wiring is shown in figure below.

Note: some older units may have different wiring, and it is important to ensure the wiring is correct.

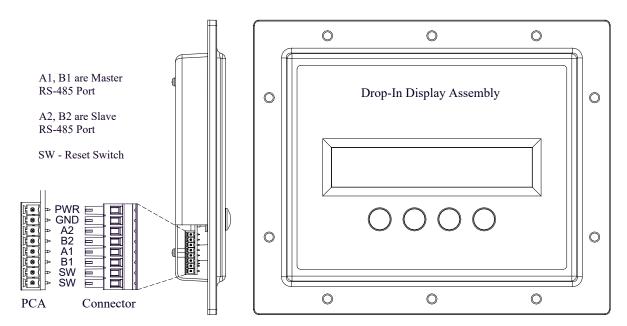


Figure 43 NEMA 4 Drop-In Display Assembly

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# 9. Customer Support and Service Policy

Teledyne Detcon Headquarters

Shipping Address: 14880 Skinner Road, Cypress TX 77429

Phone: 713.559.9200

- www.teledynegasandflamedetection.com
- detcon-service@teledyne.com
- detcon-sales@teledyne.com

All Technical Service and Repair activities should be handled by the Teledyne Detcon Service Department via phone or email (contact information given above). RMA numbers should be obtained from the Teledyne Detcon Service Department prior to equipment being returned. For on-line technical service, have the model number, part number, and serial number of product(s) in question available.

All Sales activities (including spare parts purchase) should be handled by the Teledyne Detcon Sales Department via phone or email (contact information given above).

**NOTE:** All additional parts must be supplied by Teledyne Detcon. Use of parts from a third party will void warranty and safety approvals.

**NOTE:** X40 should only be repaired by Teledyne Detcon personnel or a Teledyne Detcon trained representative.

# 10.Warranty Notice

Teledyne Detcon Inc. warrants the X-40 Integrated Alarm and Control System to be free from defects in workmanship of material under normal use and service for two years from the date of shipment on the transceiver electronics.

Teledyne Detcon Inc. will repair or replace without charge any such equipment found to be defective during the warranty period. Full determination of the nature of, and responsibility for, defective or damaged equipment will be made by Teledyne Detcon Inc. personnel.

Defective or damaged equipment must be shipped to the Teledyne Detcon Inc. factory or representative from which the original shipment was made. In all cases, this warranty is limited to the cost of the equipment supplied by Teledyne Detcon Inc. The customer will assume all liability for the misuse of this equipment by its employees or other contracted personnel.

All warranties are contingent upon the proper use in the application for which the product was intended and does not cover products which have been modified or repaired without Teledyne Detcon Inc. approval, or which have been subjected to neglect, accident, improper installation or application, or on which the original identification marks have been removed or altered.

Except for the express warranty stated above, Teledyne Detcon Inc. disclaims all warranties with regard to the products sold. Including all implied warranties of merchantability and fitness and the express warranties stated herein are in lieu of all obligations or liabilities on the part of Teledyne Detcon Inc. for damages including, but not limited to, consequential damages arising out of, or in connection with, the performance of the product.

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# 11.Specifications

**System Specifications** 

Capacity: 32 I/O Channels

Sensor Inputs: Analog 4-20mA or RS-485 Modbus<sup>TM</sup> RTU Outputs: Analog 4-20mA or RS-485 Modbus<sup>TM</sup> RTU

Warranty: One year

**Environmental Specifications** 

Operating Temperature: -10°C to +64°C Storage Temperature: -40°C to +85°C

Humidity: 0-99%RH, non-condensing

Altitude: 0 -2000m

**Electrical Specifications** 

N1P, N4X Input Voltage: 100-120/220-240VAC, 50-60Hz

11.5-30VDC

N7 Input Voltage: 11.5-30VDC

Max AC Current Rating: 2.1A/1A (110-120VAC/220-240VAC)

Max DC Current Rating: 7.5A

Power Consumption: X40-08-N4X - Total Power consumption is dependent on number of I/O

modules, number of gas sensors, and the type of gas sensors. Total power of

controller with I/O modules and gas sensors not to exceed 100 Watts.

Power Consumption: X40-32-N1P, X40-32-N4X - Total Power consumption is dependent on

number of I/O modules, number of gas sensors, and the type of gas sensors. Total power of controller with I/O modules and gas sensors not to exceed 100

Watts.

Power Consumption: X40-32-N7 – Less than 0.5W (with alarm LEDs and backlight inactive,

controller only)

RFI/EMI Protection: Complies with EN61326

Electrical Classification: NEMA 1 (X40-32-N1P), NEMA 4X (X40-08-N4X, X40-32-N4X)

NEMA 7 (X40-32-N7)

Pollution Degree: 3 Overvoltage Category: II

Safety Approvals



Certification includes NEMA 4 models only

Certified to CSA/UL/EN-61010-1

**Electrical Classification** 

Pollution degree: 3 Overvoltage category: II

Mechanical Specifications

Display:  $1^{1}/_{4}$ " x 6" Backlit LCD

Dimensions: X40-32-N1P – 10.5" W x 8" H x 12" D

X40-08-N4X – 11.85" W x 13.75" H x 6.5" D X40-32-N4X – 16" W x 17.85" H x 8.5" D X40-32-N7 – 11.05" W x 9.15" H x 2.78" D

**Wireless Specifications** 

Frequency: ISM 2.4GHz

Range: Indoor/No Line of Sight – 1,000ft

Outdoor RF Line of Sight (with directional antenna) – 1.5 Miles

Spread Spectrum: Digital-Sequence Spread Spectrum (DSSS)

Modulation: 0-OPSK

Sensitivity: -102dBm (1% PER)



# 12.Appendix

# 12.1 Hexadecimal Table

**Table 5 Hexadecimal Conversion Table** 

ID#	MSD	LSD															
0	0	0	43	2	В	86	5	6	129	8	1	172	Α	С	215	D	7
1	0	1	44	2	С	87	5	7	130	8	2	173	Α	D	216	D	8
2	0	2	45	2	D	88	5	8	131	8	3	174	Α	Е	217	D	9
3	0	3	46	2	Е	89	5	9	132	8	4	175	Α	F	218	D	Α
4	0	4	47	2	F	90	5	Α	133	8	5	176	В	0	219	D	В
5	0	5	48	3	0	91	5	В	134	8	6	177	В	1	220	D	С
6	0	6	49	3	1	92	5	С	135	8	7	178	В	2	221	D	D
7	0	7	50	3	2	93	5	D	136	8	8	179	В	3	222	D	Ε
8	0	8	51	3	3	94	5	Е	137	8	9	180	В	4	223	Е	F
9	0	9	52	3	4	95	5	F	138	8	Α	181	В	5	224	Е	0
10	0	Α	53	3	5	96	6	0	139	8	В	182	В	6	225	Е	1
11	0	В	54	3	6	97	6	1	140	8	С	183	В	7	226	Е	2
12	0	С	55	3	7	98	6	2	141	8	D	184	В	8	227	Е	3
13	0	D	56	3	8	99	6	3	142	8	Ε	185	В	9	228	Е	4
14	0	Ε	57	3	9	100	6	4	143	8	F	186	В	Α	229	Ε	5
15	0	F	58	3	Α	101	6	5	144	9	0	187	В	В	230	Е	6
16	1	0	59	3	В	102	6	6	145	9	1	188	В	С	231	Е	7
17	1	1	60	3	С	103	6	7	146	9	2	189	В	D	232	Е	8
18	1	2	61	3	D	104	6	8	147	9	3	190	В	Е	233	Е	9
19	1	3	62	3	Е	105	6	9	148	9	4	191	В	F	234	Е	Α
20	1	4	63	3	F	106	6	Α	149	9	5	192	C	0	235	Е	В
21	1	5	64	4	0	107	6	В	150	9	6	193	С	1	236	Е	С
22	1	6	65	4	1	108	6	С	151	9	7	194	С	2	237	Е	D
23	1	7	66	4	2	109	6	D	152	9	8	195	С	3	238	Е	Е
24	1	8	67	4	3	110	6	Е	153	9	9	196	С	4	239	F	F
25	1	9	68	4	4	111	6	F	154	9	Α	197	С	5	240	F	0
26	1	Α	69	4	5	112	7	0	155	9	В	198	С	6	241	F	1
27	1	В	70	4	6	113	7	1	156	9	С	199	С	7	242	F	2
28	1	С	71	4	7	114	7	2	157	9	D	200	С	8	243	F	3
29	1	D	72	4	8	115	7	3	158	9	Е	201	С	9	244	F	4
30	1	Е	73	4	9	116	7	4	159	9	F	202	С	Α	245	F	5
31	1	F	74	4	Α	117	7	5	160	Α	0	203	С	В	246	F	6
32	2	0	75	4	В	118	7	6	161	Α	1	204	С	С	247	F	7
33	2	1	76	4	С	119	7	7	162	Α	2	205	С	D	248	F	8
34	2	2	77	4	D	120	7	8	163	Α	3	206	С	E	249	F	9
35	2	3	78	4	Е	121	7	9	164	Α	4	207	С	F	250	F	Α
36	2	4	79	4	F	122	7	Α	165	Α	5	208	D	0	251	F	В
37	2	5	80	5	0	123	7	В	166	Α	6	209	D	1	252	F	С
38	2	6	81	5	1	124	7	С	167	Α	7	210	D	2	253	F	D
39	2	7	82	5	2	125	7	D	168	Α	8	211	D	3	254	F	E
40	2	8	83	5	3	126	7	Е	169	Α	9	212	D	4	255	F	F
41	2	9	84	5	4	127	7	F	170	Α	Α	213	D	5			
42	2	Α	85	5	5	128	8	0	171	Α	В	214	D	6			

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# 12.2 Hexadecimal Table

**CAUTION**: Contact a Teledyne Detcon representative prior to changing any settings in this section. Default settings are functional for the majority of applications. Any adjustments made to other items may cause the controller or various components to not work properly.



ATTENTION: Contactez un représentant Teledyne Detcon avant de modifier les paramètres de cette section. Les paramètres par défaut sont fonctionnels pour la majorité des applications. Tout ajustement apporté à d'autres éléments peut empêcher le contrôleur ou divers composants de fonctionner correctement

X40 controller setup is accomplished through the Main Menu and consists of 9 menu items:

- 1. Setup Channel Data
- 2. Set RF Silence and RF Sleep
- 3. Set Low Battery Alarms
- 4. Set Modbus Address
- 5. CXT Low Battery Threshold
- 6. Module update rates
- 7. Set COMM Baud Rates
- 8. Set Modbus<sup>TM</sup> Timeouts
- 9. Display Settings

**NOTE:** To access the Utilities Menu, advance to the View TWA and Peak menu. Hold the magnet over the ENTER marker for 20 seconds without removing it.

#### **Set Channel Data**

The Setup Channel Data menu configures each channel represented by its assigned sensor or device. When a sensor or device is added to the controller, the information can be added and/or modified in this menu.

Information to be configured is as follows:

- 1. Slave ID
- 2. Device Type
- 3. Analog Input
- 4. Decimal Point
- 5. Range
- 6. Type
- 7. RL4 Bank
- 1. Upon entering this menu, the LCD will display:

CHANNEL 1 DATA: DECIMAL POINT:#
SLAVE ID:## RANGE:####
DEVICE TYPE:XXX
ANALOG INPUT:# RL4 BANK:XXX

- 2. A flashing cursor will appear on SLAVE ID. Swipe the magnet over the markers of the up or down arrows to move the flashing cursor to the desired function. A swipe over:
  - The ENTER marker will select the function indicated by the flashing cursor.
  - The markers of the up or down arrows will change the value.
  - The ENTER marker will save the selected value and return to the flashing cursor.

**NOTE:** The SLAVE ID is the Modbus<sup>TM</sup> address in hex of the sensor or device being assigned to a specific channel. This will be a Modbus<sup>TM</sup> slave device to the X-40 controller.

#### **Device Type Value**

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The Device Type values available are 100, 700, 600 (Teledyne Detcon serial sensor models), DA4/DI4 (analog sensors) or radio module (when analog inputs are in use). Ensure that the appropriate value corresponding to the sensor or device is assigned to the indicated channel.

### **Analog Input Value**

The Analog Input is only available for analog sensors and devices. Analog sensors (DA4/DI4), the available value is 1, 2, 3 or 4 corresponding to the input position on the DA-4/DI-4 module. For a SmartWireless® CX Sensor Station or a SmartWireless® CXT Slave Controller, the available value is 1, 2, 3, or 4. A wireless radio module (RXT-320 with a Model 100 Terminal Board), the available value is 1 or 2 corresponding to the input position of the connected sensor.

#### **Decimal Point Value**

The Decimal Point value is set to 0, 1 or 2. The number of digits displayed to the right of the decimal point of the gas concentration value is as follows:

- Sensor range is less than 10, this value will be 2.
- Sensor range is between 10 and 25, this value will usually be 1.
- Sensor range is greater than 25, the value should be 0.

### Range Value

The Range value is 1-10,000 and corresponds to the gas range value of the sensor.

**NOTE:** If the range is changed, the alarm levels will have to be reset.



**CAUTION**: The range value must match the range on the sensor for proper operation.

**ATTENTION:** La valeur de la plage doit correspondre à la plage du capteur pour un fonctionnement correct.

# Type Value

The Type value is an alphanumeric string of nine characters and corresponds to the tag that is displayed with the gas concentration value. This field is used to define the gas concentration units and the gas type.

- 1. Swipe the magnet over the markers of the up or down arrows to modify the first alphanumeric character indicated by an underscore.
- 2. A swipe over the ENTER marker will select the displayed value and the next character to be changed will be indicated by an underscore.
- 3. Repeat Steps 1 and 2 to update all nine characters.
- 4. Swipe over the ENTER marker to return to the flashing cursor.

#### **RL4 Bank Value**

The RL4 Bank value can be 1, 2, 3, 4, 5, 6, 7, 8, or ALL and defines the total number of banks that the channels have been assigned. When selected, a new page allows the user to toggle the channel's relay bank assignments for all eight banks.

- 1. Swipe the down arrow marker while the flashing cursor is on RL4 BANK to scroll the display to the next channel allowing for its configuration.
- 2. A swipe of the up arrow marker while the flashing cursor is on SENSOR TYPE will return to the previous channel.

# **Set FR Silence and RF Sleep (Wireless Function Only)**

The Set RF Silence and RF Sleep menu allows the user to initiate radio silence for a predetermined amount of time, over the entire network. RF Sleep terminates communication (sleep command) between all of the wireless radio modules in the network as a power saving feature. A longer sleep time will increase delay between alarm conditions occurring and the alarms being activated. RF Silence prevents radios from interfering with other RF devices on site (remote detonators). This feature will stay on until the user turns it off. The sensors are not monitored and no alarms can be activated while RF Silence is active.

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1. Upon entering this menu, the LCD will display:

RF SILENCE AND SLEEP
RF SILENCE: | RF SLEEP: | ##:##
XX | SLEEP:XXX

- 2. Swipe the magnet over the markers of the up or down arrows to move the arrow prompt "→" to the desired location. A swipe over:
- The ENTER marker for RF SILENCE and SLEEP will toggle the value between ON and OFF.
- The ENTER marker for RF SLEEP will select the function indicated by the arrow prompt "→".
- The markers of the up or down arrows will change the value.
- The ENTER marker will save the selected value.
- The sleep timer has a range from zero to five minutes and is set in minutes and seconds.

### **Set Low Battery Alarms**

The Set Low Battery Alarms menu establishes low battery alarm thresholds for wireless radio modules using Teledyne Detcon's Smart Battery Pack interfaced to the controller.

1. Upon entering this menu, the LCD will display:

LOW BATTERY ALARM:						
TTE(DD:HH:MM):	<b>SOC(%):</b>					
##:##:##	##%					
	ALARM STATIONS ONLY					

- 2. To change the TTE (time to empty in days, hours and minutes) and/or SOC (state of charge in percentage) values, swipe the magnet over the markers of the up or down arrows to move the cursor to the desired field. A swipe over:
- The ENTER marker will select the field indicated by the cursor and enclose the value in brackets.
- While in brackets, the markers of the up or down arrows will change the value.
- Another swipe over the ENTER marker will save the selected value.
- A swipe of the PROG marker at any time while setting the TTE or SOC will escape out of the current field with no changes saved.

The recommended value for the TTE should be five days and applies to all battery powered wireless radio modules transceivers other than alarm stations. The SOC value applies to alarm stations **only** and the recommended value should be 25%. The blue LED on the controller will be activated and begin flashing when any battery in the network falls below the set thresholds.

# Set Modbus<sup>TM</sup> Address

The SET Modbus<sup>™</sup> Address menu establishes the serial address of the X-40 controller when being polled by another master device through the RS-485 Modbus<sup>™</sup> RTU slave port (COMM2).

1. Upon entering this menu, the LCD will display:

# MODBUS ADDRESS: ###

- 2. This value can be changed by performing a swipe:
- Over the ENTER marker and then swiping
- Over the markers of the up or down arrows.
- Another swipe over the ENTER marker will save the selected value.
- 3. Ensure that the range of values for the Modbus $^{\text{TM}}$  address is 1-127 in decimal value.

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### **CXT Low Battery Threshold**

CXT sensors offer the option to use non-rechargeable batteries. If this option is used, the low battery alarm is determined by the voltage of the batteries. When the battery voltage falls below the threshold, the low battery fault will be activated.

This value can be changed by performing a swipe:

- Over the ENTER marker and then swiping
- Over the markers of the up or down arrows.
- Another swipe over the ENTER marker will save the selected value.

### **Module Update Interval**

The AO-4 outputs and battery life readings from the wireless radio modules on the X40 are updated periodically. This menu setting controls the rate at which these updates occur. The default rate is 60 seconds.

This value can be changed by performing a swipe:

- Over the ENTER marker and then swiping
- Over the markers of the up or down arrows.
- Another swipe over the ENTER marker will save the selected value.

#### **Set COMM Baud Rates**

The Set COMM Baud Rates menu displays the current baud rate settings for COMM1 (master) and COMM2 (slave).

Upon entering this menu, the LCD will display:

SET COMM BAUD RATES: COMM1 BAUD RATE:9600 COMM2 BAUD RATE:9600

**NOTE:** The value shown is pre-configured to 9600 and should not be altered unless directed to do so by Teledyne Detcon factory personnel.

#### Set Modbus<sup>TM</sup> Timeouts

The Set Modbus<sup>TM</sup> Timeouts menu establishes the response timeout for Modbus<sup>TM</sup> communications and the inter-poll delay. Response timeout is the amount of time in milliseconds the X40 controller will wait for a sensor to respond to a poll request. Inter-poll delay is the amount of time in milliseconds the X40 will wait after receiving a poll response from one sensor before it polls the next sensor. Ten missed poll responses will result in the sensor being declared in COMM ERR. The range of values for the response timeout is 100-1000 milliseconds and 10-255 milliseconds for the inter-poll delay. The recommended value for the response timeout is 1000 and 250 for the inter-poll delay.

1. Upon entering this menu, the LCD will display:

SET MODBUS TIMEOUTS: RESPONSE TIMEOUT:### INTERPOLL DELAY:###

- 2. Values can be changed by swiping the magnet over the markers of the up or down arrows to move the arrow prompt "→" to the desired function. A swipe over:
- The ENTER marker will select the function indicated by the arrow prompt " $\rightarrow$ ".
- The markers of the up or down arrows will change the value.
- The ENTER marker will save the selected value.

# **Display Settings**

The Display Settings menu customizes the brightness, contrast and backlight duration of the display. Values for brightness and contrast range between 0 and 100. Available values for the backlight timeout function (turn off due to inactivity) are OFF, 10 seconds, 30 seconds and 1 to 5 minutes.



1. Upon entering this menu, the LCD will display:

# DISPLAY SETTINGS BRIGHTNESS: ### BACKLIGHT TIMEOUT: #:## CONTRAST: ###

- 2. These values can be changed by swiping the magnet over the markers of the up or down arrows to move the arrow prompt "→" to the desired function. A swipe over:
- The ENTER marker will select the function indicated by the arrow prompt "→".
- The markers of the up or down arrows will change the value.
- The ENTER marker will save the selected value.

# 13. Spare Parts and Wireless Accessories

Part Number	Spare Parts
360-ML1000-024	Power Supply 4.2A
975-041402-000	DI-4 Input Module
976-041400-000	DA-4 Input Module
975-041401-000	AO-4 Output Module
975-041400-000	RL-4 Output Module
327-000000-000	Programming Magnet
500-003087-100	Transient Protection Module
500-005156-000	AC/DC Converter 4W
500-005142-100	NEMA 7 X40 Display Control PCA
500-005142-200	N1P / N1R Display Control PCA
949-005142-200	NEMA 4 X40 Drop-In Display Control Assembly
Part Number	Wireless Accessories
976-00132D-000	RXT-320 Transceiver Din-Rail Mounted
976-0003A4-200	2.4Ghz NEMA4 8" Antenna, 8" cable
976-000320-316	Wireless 320 Transceiver (NEMA 7 Radio Module)
500-005168-100	Model 100 Terminal Board
897-850000-010	NEMA 7 Aluminum Condulet w Solid Cover
897-850901-010	NEMA 7 Aluminum Condulet w window Cover
897-850902-010	NEMA 7 Aluminum Condulet w Extended Cover
960-202200-000	Condensation prevention packet (For condulet, replace annually)
960-202200-000 8522-750	Condensation prevention packet (For condulet, replace annually)  3/4" NPT Plug
8522-750	³/₄" NPT Plug

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# 14.Revision Log

Revision	Date	Changes made	Approval
0.0	02/07/11	Initial Release.	LU
0.1	03/18/11	Corrected AO-4 modbus address range. Corrected enclosure	LU
		dimensions for 32 channel enclosure and added drawing for 8	
		channel enclosure. Revised DC input voltage specs.	
1.0	07/29/11	Updates and modifications made relating to addition of different	LU
		enclosure types for the X40. Added 4 new menus: Auto Configure,	
		Low Battery Alarms, Time and Date and TWA and Peak. Added	
		section relating to SD card.	
1.1	08/10/11	Made minor clarifications to sections 5.4.2, 5.5, 7.3.4, 7.3.7,	LU
		7.3.13 and 7.3.15. Modified RL-4 Table 2.	
2.0	11/14/11	Changed N4X enclosure to include the Drop-In Assembly	LU
2.1	04/02/12	Updates to terminal boards used, verbiage on units with alarm	LU
2.2	07/10/12	Updated cable recommendation to General Cable Commodore	LU
3.0	12/07/12	Updated to cover Auto Configure and Utilities	LU
3.1	09/10/13	Changes for CE Approvals	LU
3.2	11/22/13	Add replacement of Control Assembly (NEMA 4 and 7)	LU
3.3	05/16/14	Add information to interface with Site Sentinel CX and CXT's	LU
3.4	01/05/15	Corrected Section 3.5	LU
3.5	09/02/15	Corrected Section 3.7, added details about Modbus Slave comms	LU
3.6	01/20/20	Updated Company Information	MM
3.7	02/03/21	Updated Company Address	KM
3.8	01/17/23	TUV Certification Updates	KM

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